

BAS5 for Xeon

Maintenance Guide



HPC

BAS5 for Xeon

Maintenance Guide

Hardware and Software

April 2008

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Preface

Intended Readers

This guide is intended for use by qualified personnel, in charge of maintaining and troubleshooting the Bull HPC clusters of NovaScale R4xx nodes, based on Intel® Xeon® processors.

Prerequisites

Readers need a basic understanding of the hardware and software components that make up a Bull HPC cluster, and are advised to read the documentation listed in the Bibliography below.

Structure

This guide is organized as follows:

- Chapter 1. *Stopping/Restarting Procedures*
Describes procedures for stopping and restarting Bull HPC cluster components.
 - Chapter 2. *Day to Day Maintenance Operations*
Describes how to undertake different types of maintenance operations using the set of maintenance tools provided with Bull HPC clusters.
 - Chapter 3. *Troubleshooting*
This chapter aims to help the user develop a general, comprehensive methodology for identifying, and solving problems on- and off-site.
 - Chapter 4. *Updating the BMC Firmware on NovaScale R421/R422*
Describes how to update the **BMC** firmware on NovaScale and R421 and R422 systems.
 - Chapter 5. *Updating the firmware for the InfiniBand switches*
Describes how to update the firmware for the **MegaRAID** card
 - Chapter 6. *Updating the firmware for the MegaRAID Card*
Describes how to update the **Voltaire** switch firmware.
 - Chapter 7. *Managing the BIOS on NovaScale R4xxx Machines*
Describes how to update the BIOS on NovaScale R421 and R422 machines. It also defines the recommended settings for the BIOS parameters on NovaScale R4xxx machines.
- Glossary and Acronyms*
Lists the Acronyms used in the manual.

Bibliography

- Bull HPC BAS5 for Xeon Installation and Configuration Guide (86 A2 87EW)
- Bull HPC BAS5 for Xeon Administrator's Guide (86 A2 88EW)
- Bull HPC BAS5 for Xeon User's Guide (86 A2 89EW)
- Bull HPC BAS5 for Xeon System Release Bulletin (86 A2 64EJ)
- NovaScale Master Remote HW Management CLI Reference Manual (86 A2 88EM)
- Bull Voltaire Switches Documentation CD (86 A2 79ET)
- StoreWay Optima 1250 Quick Start Guide (86 A1 52EW)
- StoreWay Optima 1250 Installation and User Guide (86 A1 53EW)
- StoreWay Master User Guide (86 A2 38ET)
- StoreWay Master Installation Guide (86 A2 37ET)

For clusters which use the **PBS Pro** Batch Manager:

- PBS Professional 9.0 *Administrator's Guide* (on PBS Pro CD-ROM)
- PBS Professional 9.0 *User's Guide* (on PBS Pro CD-ROM)

Highlighting

- Commands entered by the user are in a frame in "Courier" font. Example:

```
mkdir /var/lib/newdir
```

- Commands, files, directories and other items whose names are predefined by the system are in "Bold". Example:
The **/etc/sysconfig/dump** file.
- Text and messages displayed by the system to illustrate explanations are in "Courier New" font. Example:
BIOS Intel
- Text for values to be entered in by the user is in "Courier New". Example:
COM1
- *Italics* identifies referenced publications, chapters, sections, figures, and tables.
- < > identifies parameters to be supplied by the user. Example:
<node_name>



Warning

A **Warning** notice indicates an action that could cause damage to a program, device, system, or data.



CAUTION

A *Caution* notice indicates the presence of a hazard that has the potential of causing moderate or minor personal injury.

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Chapter 1. Stopping/Starting Procedures

This chapter describes procedures for stopping and restarting Bull HPC cluster components, which are mainly used for maintenance purposes.

The following procedures are described:

- 1.1 *Stopping/Restarting a Node*
- 1.2 *Stopping/Restarting an Ethernet Switch*
- 1.3 *Stopping/Restarting a Backbone Switch*
- 1.4 *Stopping/Restarting the HPC Cluster*

1.1 Stopping/Restarting a Node

1.1.1 Stopping a Node

Follow these steps to stop a node:

1. Stop the customer's environment. Check that the node is not running any applications by using the **SINFO** command on the management node. All customer applications and connections should be stopped or closed including shells and mount points.
2. Un-mount the filesystem.
3. Stop the node:

From the management node enter:

```
nsctrl poweroff <node_name>
```

This command executes an Operating System (OS) command. If the OS is not responding it is possible to use:

```
nsctrl poweroff_force <node_name>
```

Wait for the command to complete.

4. Check the node status by using:

```
nsctrl status <node_name>
```

The node can now be examined, and any problems which may exist diagnosed and repaired.

1.1.2 Restarting a Node

To restart a node, enter the following command from the management node:

```
nsctrl poweron <node_name>
```



Note:

If during the boot operation the system detects an error (temperature or otherwise), the node will be prevented from rebooting.

Check the node status

Make sure that the node is functioning correctly, especially if you have restarted the node after a crash:

- Check the status of the services that must be started during the boot. (The list of these services is in the `/etc/rc.d` file).
- Check the status of the processes that must be started by a `cron` command.
- The mail server, `syslog-ng` and `ClusterDB` must be working.
- Check any error messages that the mails and log files may contain.

Restart SLURM and the filesystems

If the previous checks are successful, reconfigure the node for SLURM and restart the filesystems.

1.2 Stopping/Restarting an Ethernet Switch

- Power-off the Ethernet switch to stop it.
- Power-on the Ethernet switch to start it.
- If an Ethernet switch must be replaced, the MAC address of the new switch must be set in the ClusterDB. This is done as follows:
 1. Obtain the MAC address for the switch (generally written on the switch, or found by looking at DHCP logs).
 2. Use the **phpPgAdmin** Web interface of the DATABASE to update the switch MAC address (<http://IPaddressofthemanagementnode/phpPgAdmin/> user=clusterdb and password=clusterdb).
 3. In the **eth_switch** table look for the **admin_macaddr** row in the line corresponding to the name of your switch. Edit and update this MAC address. Save your changes.
 4. Run a **dbmConfig** command from the management node:

```
dbmConfig configure --service sysdhcpd --force -nodeps
```

5. Power-off the Ethernet switch.
6. Power-on the Ethernet switch.

The switch issues a DHCP request and loads its configuration from the management node.



See:

Bull HPC BAS5 for Xeon Administrator's Guide for information about how to perform changes for the management of the ClusterDB.

1.3 Stopping/Restarting a Backbone Switch

The backbone switches enable communication between the cluster and the external world. They are not listed in the **ClusterDB**. It is not possible to use ACT for their reconfiguration.

1.4 Stopping/Restarting the HPC Cluster

1.4.1 Stopping the HPC Cluster

To stop the whole cluster in complete safety it is necessary to launch different stages in sequence. The **nsclusterstop** script includes all the required stages.

1. From the management node, run:

```
# nsclusterstop
```

2. Stop the management node.

1.4.2 Starting the HPC Cluster

To start the whole cluster in complete safety it is necessary to launch different stages in sequence. The **nsclusterstart** script includes all the required stages.

1. Start the Management Node.
2. From the Management Node, run:

```
# nsclusterstart
```



See:

Chapter 2 details the **nsclusterstop/nsclusterstart** commands and their associated configuration files.

Chapter 2. Day to Day Maintenance Operations

2.1 Maintenance Tools Overview

This chapter describes a set of maintenance tools provided with a Bull HPC cluster. These tools are mainly Open Source software applications that have been optimized, in terms of CPU consumption and data exchange overhead, to increase their effectiveness on Bull HPC clusters which may include hundred of nodes. The tools are usually available through a browser interface, or through a remote command mode. Access requires specific user rights and is based on secured shells and connections.

Function	Tool	Purpose	Page
Administration	ConMan ipmitool	Managing Consoles through Serial Connection	2-2
	nsclusterstop / nsclusterstart	Stopping/Starting the cluster	2-5
	nsctrl	Managing hardware (power on, power off, reset, status, ping checking temperature, changing bios, etc)	2-7
	Remote Hardware Management CLI		2-8
	syslog-ng	System log Management	2-8
	lptools (lputils, lpflash)	Upgrading Emulex HBA Firmware (Host Bus Adapter)	2-13
Backup / Restore	mkCDrec	Backing-up and restoring data	2-15
Monitoring	ibstatus, ibstat	Monitoring InfiniBand networks	2-18
	IBS tool	Providing information about and configuring InfiniBand switches	2-20
	switchname	Monitoring Voltaire switches	2-30
	lsiocfg	Getting information about storage devices	2-33
	pingcheck	Checking device power state	2-36
Debugging	ibdoctor/ibtracert	Identifying InfiniBand network problem	2-37
	crash/proc/kdump	Runtime debugging and dump tool	2-40
Testing	postbootchecker	Making verifications on nodes as they start	2-42

Table 2-1. Maintenance Tools

2.2 Maintenance Administration Tools

2.2.1 Managing Consoles through Serial Connections (conman, ipmitool)

The serial lines of the servers are the communication channel to the firmware and enable access to the low-level features of the system. This is why they play an important role in the system **init** surveillance, or in taking control if there is a crash or a debugging operation is undertaken.

The serial lines are brought together with Ethernet/Serial port concentrators, so that they are available from the Management Node.

- **ConMan** can be used as a console management tool.
See 2.2.1.1 *Using ConMan*.
- **ipmitool** allows you to use a Serial Over Lan (SOL) link.
See 2.2.1.2 *Using ipmi Tools*.



Note:

Storage Units may also provide console interfaces through serial ports, allowing configuration and diagnostics operations.

2.2.1.1 Using ConMan

The **ConMan** command allows the administrator to manage all the consoles, including server consoles and storage subsystem consoles, on all the nodes. It maintains a connection with all the lines that it administers. It provides access to the consoles and uses a logical name. It supports the key sequences that provide access to debuggers or to dump captures (Crash/Dump).

ConMan is installed on the Management Node.

The advantages of ConMan on a simple telnet connection are as follows:

- Symbolic names are mapped per physical serial line.
- There is a log file for each machine.
- It is possible to join a console session or to take it over.
- There are three modes for accessing the console: monitor(read-only), interactive(read-write), broadcast(write only).

Syntax:

conman <OPTIONS> <CONSOLES>

- | | |
|----------------|--|
| -b | Broadcast to multiple consoles (write-only). |
| -d HOST | Specify server destination. [127.0.0.1:7890] |
| -e CHAR | Specify escape character. [&] |
| -f | Force connection (console-stealing). |

-F FILE	Read console names from file.
-h	Display this help file.
-j	Join connection (console-sharing).
-l FILE	Log connection output to file.
-L	Display license information.
-m	Monitor connection (read-only).
-q	Query server about specified console(s).
-Q	Be quiet and suppress informational messages.
-r	Match console names via regex instead of globbing.
-v	Be verbose.
-V	Display version information.

Once a connection is established, enter "&." to close the session, or "&?" to display a list of currently available escape sequences.

See the **conman** man page for more information.

Examples:

- To connect to the serial port of NovaScale `bull47`, run the command:

```
conman bull47
```

Configuration File:

The `/etc/conman.conf` file is the conman configuration file. It lists the consoles managed by conman and configuration parameters.

The `/etc/conman.conf` file is automatically generated from the ClusterDB information. To change some parameters, the administrator should only modify the `/etc/conman-tpl.conf` template file, which is used by the system to generate `/etc/conman.conf`. It is also possible to use the **dbmConfig** command. See the *Cluster Data Base Management* chapter for more details.

See the **conman.conf** man page for more information.



Note:

The **timestamp** parameter, which specifies the watchdog frequency, is set to 1 minute by default. This value is suitable for debugging and tracking purposes but generates a lot of messages in the `/var/log/conman` file. To disable this function, comment the line `SERVER timestamp=1m` in the `/etc/conman-tpl.cfg` file.

2.2.1.2

Using ipmi Tools

The **ipmitool** command provides a simple command-line interface to the **BMC** (Baseboard Management Controller).

To use **SOL** (Serial Over Lan) interface, run the following command:

```
ipmitool -I lanplus -C 0 -U <BMC_user_name> -P <BMC_password>
-H <BMC_IP_Address> sol activate
```

BMC_user_name, **BMC_password** and **BMC_IP_Address** are values defined during the configuration of the BMC and are taken from those in the **ClusterDB**. The standard values for user name/password are administrator/administrator.

ipmitool Command Useful Options

- To start a remote SOL session (to access the console):

```
ipmitool -I lanplus -C 0 -H <ip addr> sol activate
```

- To reset the BMC and return to BMC shell prompt:

```
ipmitool -I lanplus -C 0 -H <ip addr> bmc reset cold
```

- To edit the FRU of the machine:

```
ipmitool -H <ip addr> fru print
```

- To edit the network configuration:

```
ipmitool -I lan -H <ip_addr> lan print 1
```

- To trigger a dump (signal INIT):

```
ipmitool -H <ip addr> power diag
```

- To power down the machine:

```
ipmitool -H <ip addr> power off
```

- To perform a hard reset:

```
ipmitool -H <ip addr> power reset
```

- To display the events recorded in the System Event Log (SEL):

```
ipmitool -H <ip addr> sel list
```

- To display the MAC address of the BMC:

```
ipmitool -I lan -H <ip addr> raw 0x06 0x52 0x0f 0xa0 0x06 0x08 0xef
```

Note: If **-H** is not specified, the command will address the BMC of the local machine.

- To know more about the **ipmitool** command, enter:

```
ipmitool -h
```

2.2.2 Stopping/Starting the Cluster (nsclusterstop, nsclusterstart)

The **nsclusterstop/nsclusterstart** scripts are used to stop or start the whole HPC cluster. These scripts launch in sequence the various stages making it possible to stop/start the cluster in full safety. For example, the stop process includes the following main steps:

- checking the various equipment,
- stopping the file systems (Lustre for example),
- stopping the storage devices,
- stopping the nodes, except the Management Node(s).

nsclusterstop and **nsclusterstart** use two configuration files: **/etc/clustmngt/nsclusterstart.conf** and **/etc/clustmngt/nsclusterstop.conf** files whose values can be changed. The **--file** option allows you to specify another configuration file. These files define:

- the delay parameters between the different stages required to stop/start the cluster
- the sequence in which the group of nodes should be stopped/started. You can run **dmbGroup show** to display the configured groups.

Usage:

```
/usr/sbin/nsclusterstop [-h] | [-f, --file <filename>]
```

```
/usr/sbin/nsclusterstart [-h] | [-f, --file <filename>]
```

Options:

- file <filename>, -f** Specify a configuration file (default: **/etc/clustmngt/nsclusterstart.conf** or **/etc/clustmngt/nsclusterstop.conf**).
- h** Display **nsclusterstart/nsclusterstop** help.
- only_test , -o** Display the commands that would be launched according to the specified options. This is a testing mode, no action is performed.
- verbose, -v** Verbose mode.

Configuration files:

```
/etc/clustmngt/nsclusterstart.conf
```

```
#####  
#  
# First Part is used to control the power supply of DDN and servers  
#  
#####  
  
# time to wait for all diskarrays ok, before powering the powerswitches on  
disk_arrays_StartDelay = 300
```

```

# time to wait for all powerswitches being ON after a poweron
couplets_StartDelay = 60

# time to wait after poweron for all servers being effectively operational
servers_StartDelay = 480

#####
#
# Following part is used to control the order to start nodes groups
#
#####

# GROUP <nb simultaneous poweron> <time to wait> <period to wait> <time to
wait after this GROUP>

IO 5 1 5 5
META 5 1 5 5
COMP 5 1 5 5

```

/etc/clustmngt/nsclusterstop.conf

```

#####
#
# First Part is used to control the power supply of DDN and servers
#
#####

# time to wait after poweroff for all servers being effectively down
servers_StopDelay = 180

# time to wait for ddn processing shutdown
ddnShutdown_Time = 180

# time to wait after poweroff for all powerswitches being OFF
couplets_StopDelay = 30

#####
#
# Following part is used to control the order to stop nodes groups
#
#####

# GROUP <nb simultaneous poweron> <time to wait> <period to wait> <time to
wait after this GROUP>

COMP 5 1 5 5
META 5 1 5 5
IO 5 1 5 5

```

2.2.3 Managing hardware (nsctrl)

The **nsctrl** command carries out various tasks related to hardware. This command must be run from the Management Node. The tasks can be performed on any type of node (Compute Node, I/O Node, etc.) except the Management Node.

Usage:

```
/usr/sbin/nsctrl [options] <action> [<nodes>]
```

General Options:

--debug	Debug mode (more than verbose).
--dbname name	Specify database name.
--force, -f	Do not ask for confirmation or state checking.
--group, -g	Specify a group of nodes. You can use the dbmGroup show command to display the defined groups.
--help, -h	Display nsctrl help.
--interval, -i	Specify the number of nsm calls before waiting the period defined by the --time option.
--jobs, -j	Number of simultaneous nsm actions (for example, with -j 5 you can run 5 simultaneous nsmpower processes). Default = 30.
--only_test, -o	Display the NS Commands that would be launched according to the specified options and action. This is a testing mode, no action is performed.
--time, -t	Time to wait after the number of nsm calls defined by the --interval option.
--verbose, -v	Verbose mode.

Specifying nodes:


The nodes are specified as follows: **basename[i,j-k]** .

If no nodes are explicitly specified, **nsctrl** uses the nodes defined by the **--pap** or **--group** option.

Actions:

poweron
poweroff
poweroff_force
reset
status
ping

Examples:

 **Note:** In the following examples the `-o` option (`--only_test`) is used to display which NS Commands would be launched for the specified action.

- To power off node `ns1`, enter:

```
# nsctrl -o poweroff_force ns1

ns1 : /usr/NSMasterHW/bin/nsmpower.sh -a off_force -m ipmilan
-H ns1 -u user2
```

- To ping node `ns1`, enter:

```
# nsctrl -o ping ns1

ns1 : ping -c 1 ns1
```

2.2.4 Remote Hardware Management CLI (NS Commands)

The Remote Hardware Management CLI (Command Line Interface) is a set of commands that perform hardware tasks on Bull HPC, these are also known as NS Commands. These commands provide the administrator with an easy way to automate scripts to power on/off and to get hardware information about the nodes.

2.2.5 Managing System Logs (syslog-ng)

For security and tracking purposes, and also to decrease the amount of administration work resulting from the size of the cluster, all the system logs are centralized on the Management Node. There are two ways to send system log information to the Management Node:

- The logs are collected on each node, using standard mechanisms for archival and log file permutation. Various utilities ensure compression, transfer and archival of these log files on the Management Node in asynchronous mode. A centralized operation is performed on the Management Node, in order to extract and search events according to the criterion required for example date, type, gravity, and so on.

This asynchronous process facilitates curative actions for the incidents that have occurred on the cluster.

- Some events are immediately reported to the Management Node. Filters are used, which specify the type and gravity level of the events that have to be transferred immediately.

This synchronous process instantaneously gives the administrator a global view of system events.

syslog-ng (Syslog New Generation) is the powerful system log manager used on Bull HPC clusters to manage cluster system logs and includes the following features:

- The ability to filter messages based on content using regular expressions.
- Encoding and authentication of the network traffic.
- Forwarding logs using TCP and UDP protocols.
- Log compression.

2.2.5.1 Configuring syslog-ng

syslog-ng is installed on the cluster using the default configuration. The scripts used to transfer log files are also installed. The administrators can modify the default configuration according to their needs.

The `/etc/syslog-ng/syslog-ng.conf` file contains the configuration parameters for **syslog-ng**. This file is divided into five sections:

options section	General options
source section	Source events
destination section	Log destinations
filter section	Filter definitions
log section	Actions to be performed on messages

options Section

Any general parameters may be configured in the options section. An example is below:

```
# Start of options area
options {
    sync (0);          # Number of events before writing in the logs
    time_reopen (10); # Wait 10s before reconnecting if the connection
                      # failed. Used when logs are centralized through network
    #time_reap (number);# Closes a log file that is not accessed after
                      # "number" seconds
    log_fifo_size (1000); # number of event lines stored, before writing
                          # them.
                      # Enables events to be taken quickly into account
                      # and to free the process that has generated them.
    long_hostnames (off); # Usage of long names
    use_dns (no) # Usage of DNS to find addresses
    use_fqdn (no); # Usage of machine short name
    owner("root"); # logs owner
    group("root"); # logs group
    perm("644"); # logs rights mask
    keep_hostname (yes);#
    create_dir (yes); # Create directories for log storage
    use_time_recv(no); # Local time will be used instead of the time
                      # written in the logs
    #gc_idle_threshold(100); # The garbage collector is started after 100
                          # events if syslog-ng is inactive.
    #gc_busy_threshold(100); # The garbage collector is started after
                          # 3000 events if syslog-ng is active.
};
```

source Section

The source section defines the log source from the following: network, local files, peripheral, pipe, stream.

Syntax:

```
source <identifier>  
{source-driver(params); source-driver(params); etc.};
```

For example, the following lines are suitable for a Linux system. They enable the `/dev/log` stream to be read and also to receive syslog-ng internal messages and to handle kernel starting messages:

```
source src {  
    unix-stream("/dev/log");  
    internal();  
    file("/proc/kmsg");  
};
```

Possible sources are as follows:

unix-stream(<filename>)	Stream pipes (used in Linux).
file(<filename>)	File data (Linux kernel messages for example).
pipe(<filename>)	Named pipes (for interfacing with Nagios for example).
tcp(<ip>,<port>) and udp(<ip>,<port>)	To listen on an address and a port.
internal()	syslog-ng internal messages.

destination Section

This section defines the destination of the logs.

Syntax:

```
destination <identifier>  
{ destination-driver(params); destination-driver(params); etc.};
```

The possible destinations are the following ones:

file(<filename>)	To send to a file.
tcp(<ip>,<port>) and udp(<ip>,<port>)	To send the logs on the network to another machine.
unix-stream(<filename>)	To send to stream pipes (used in Linux).
userrtyr(<user>)	To send to the <user > consoles, but only if this user is connected. You can use the "*" character to specify that the messages have to be sent to all users.
program(<commandtorun>)	To send towards a program.

Examples :

You can specify several destination directives in a destination section, as in the following example:

```
destination debug {file("/var/log/debug.log"); };
destination messages {file("/var/log/messages.log"); };
destination console {usertty("root"); };
destination xconsole {pipe("/dev/xconsole"); };
destination mail2admin {program("/usr/bin/MailToAdmin"); };
destination full{
file("/dev/tty12");
file("/var/log/full.log" log_fifo_size(2000));
};
```



Note: You can add specific options such as `log_fifo_size(2000)` as shown in the example above.

In the following example, all the logs will be sent to the Management Node, whose address is 192.168.0.100:

```
destination central_log {tcp ("192.168.0.100" port(514); }
```

Using Macros:

It may be useful to use macros to set intelligible names for your destination files. Predefined macros exist, such as FACILITY, PRIORITY or LEVEL, DATE, FULLDATE, ISODATE, YEAR, MONTH, DAY, HOUR, MIN, SEC, FULLHOST, HOST. Some examples are below:

```
destination full {
file("/dev/tty12");
file("/var/log/full_${DAY}-${MONTH}-${YEAR}.log"
owner("root")
group("adm")
perm(0640));
};
```

```
destination hosts {
file("/var/log/HOSTS/${HOSTS}/${FACILITY}/${YEAR}/${MONTH}/${DAY}/${FACILITY}${YEAR}
${MONTH}${DAY}"
owner("root")
group("adm")
perm(0600)
dir_perm(0700)
create_dirs(yes));
};
```



Note: Do not forget to remove or archive older files regularly.

filter Section

This section describes the filtering mechanism for events.

Syntax:

filter <identifier> {expression; };

The filters are defined by the following keywords:

facility (facility[, facility])	To filter by type.
level (pri[, pri1, .. pri2 [, pri3]])	To filter by priority or level.
program (regexp)	To filter by the name of the program that has generated the message.
host (regexp)	To filter by the regular expression of the name of the host that has sent the message.
match (regexp)	To filter by a regular expression.
filter (filtername)	To use another filter.

All keywords may be used several times. The expressions can contain the AND, OR and NOT operators.

Examples:

```
filter f_iptables { match("IN=.*OUT=.*MAC=.*"); };
filter f_snort { match("snort: "); };
filter f_full { not filter(f_snort) AND NOT filter(f_iptables); };
filter f_messages { level(info..warn) AND NOT facility(auth, authpriv,
mail, news); };
```

log Section

In this section you define how the messages will be processed using source, destination and filters commands defined in the previous sections.

Syntax:

```
log { source(s1); source(s2); ...
filter(f1); filter(f2); ...
destination(d1); destination(d2);
flags(flag1[, flag2...]); };
```

Examples:

```
log { source(src);
filter(f_news); filter(f_notice);
destination(newsnotice);
};
log { source(src);
destination(full);
};
```

2.2.6 Upgrading Emulex HBA Firmware with Iptools

Iptools is a set of two utilities for upgrading Emulex HBA firmware. These two utilities are:

- **lputil**: low level tool used to interact with Emulex HBA
- **lpflash**: high level script used to upgrade firmware of a set of Emulex HBA.

Emulex driver (**lpfc** module) has to be loaded when using **Iptools** (check with **lsmod**).

Firmware updates are available from Emulex Web site.

On a node, you can get the current FW level from all the Emulex HBA using the **lsiocfg** tool ("getting information about storage devices").



Warning: Be sure that FC devices are not being used when upgrading the Emulex HBA firmware.

2.2.6.1 lputil

This low level tool should not be used in standalone mode. Please refer to on-line help when using this tool.

2.2.6.2 lpflash

lpflash flashes Emulex HBAs with the specified firmware file. **lpflash** may be used to upgrade in one shot all the HBAs on a server.

Syntax:

```
lpflash <-m LP_Model -f path_to_firmware [-v]> | <-h> | <-V>
```

Flags:

-m model	Emulex HBA model to flash (case insensitive)
-f file	firmware file
-v	verbose mode
-h	displays help
-V	displays version

Example:

```
lpflash -m lp11000 -f /tmp/bd210a7.all
```

This command will upgrade all LP11000 HBA to 2.10A7 firmware.

2.2.6.3

Upgrade Emulex Firmware on Multiple Nodes

Running the `pdcp` / `pdsh` commands, Emulex firmware can be upgraded in one shot on a set of nodes:

- use `pdcp` to copy the new firmware file on all the nodes
- use `pdsh` to run `lpflash` on these nodes.

Example:

The following commands copy the Emulex firmware file on to nodes `node1`, `node2` and `node3`, and then upgrade all Emulex LP11000 HBA on these nodes with firmware 2.10A7:

```
pdcp -w "node1,node2,node3" bd210a7.all /tmp/  
pdsh -w "node1,node2,node3" lpflash -m lp11000 -f /tmp/bd210a7.all
```

2.3 Saving and Restoring the System (mkCDrec)

To save and restore the Management Node system, use the **mkCDrec** (make CD-ROM recovery). **mkCDrec** is an Open Source tool used to create a bootable system image which includes Linux system save. The image is used to restore the system after a problem, such as a disk crash or system intrusion, has occurred.

The backups are generally on CD-ROM or DVD-ROM, or on an off-line disk, preferably in read-only mode, or on NFS mounted disk or tape. The backups are protected and are inaccessible for non-authorized users.

The **mkCDrec** tool can be used for the following functions:

- To restore software. After booting from the **mkCDrec** CD-ROM or DVD-ROM, the `/etc/recovery/start-restore.sh` script will do the following:
 - Restore the complete system after a problem of some kind, for example a disk crash or a system intrusion.
 - Restore a particular disk using the backup source.
 - Restore a backup of a disk onto a new (bigger) disk in the system.
- To make multiple backup copies.
- As a rescue tool, for example to do **fsck** operations or to diagnose what's wrong with the system. See the **mkCDrec** utilities in order to add more tools to your rescue CD-ROM or DVD-ROM.
- To “clone” a disk to another disk even when the target disk is smaller in size than the original disk, as long as there is room for the data. The `clone-dsk.sh` script will calculate the partition layout for you.
- It is possible to make multi-volume CD-ROMs so backups can be split up. It is also possible to backup all the data required for booting onto a CD-ROM, in order to obtain a bootable CD-ROM, and to save other data onto TAPE.
- To restore a single file system to an existing partition, using the `restore-fs.sh` command. The user can select the target file system type which has to be formatted. The command has no arguments.
- To set-up or migrate to LVM, Software RAID, or another type of file system if the kernel permits it.
- To increase or decrease the partition size with the help of the **mkCDrec** utilities.



Note:

mkCDrec is designed for system backups. It is not the objective of **mkCDrec** to backup all system data and it is recommended to regularly backup all your data using another method.

A typical example of usage is to run **mkCDrec** every night for a system and store the ISO images on another system via **NFS**. In case of a problem it will be possible to burn the saved image onto a CD-ROM/DVD-ROM and then to restore the system.

What follows is an overview about configuring and using **mkCDrec**. For more information please refer to <http://mkcdrec.sourceforge.net>

2.3.1 Configuring mkCDrec

The `/var/opt/mkcdrec/Config.sh` file contains the configuration parameters for **mkCDrec**. All parameters have a default value. However, it is recommended that the following values are checked, either to verify that they fit your needs, or to define your own values in order to generate a coherent, but not too large, system backup.

BURNCDR	(Y or N) "Y" means that the CD-ROM/DVD-ROM will be burned directly from the machine. "N" means that ISO images of the CD-ROM/DVD-ROM will be created.
ISOFS_DIR	Path of the temporary directory used before creating the ISO images. Ensure that this directory is large enough to store the contents of a CD-ROM/DVD-ROM.
TMP_DIR	Path of the temporary directory used by mkCDrec .
DVD_DRIVE	(1 or 0) Set "0" to create CD-ROM backups or "1" to create DVD backups.
MAXCDSIZE	Maximum size of the created images (in kbs). Example: 4200000 for DVD-ROM, 620000 for CD-ROM.
CDREC_ISO_DIR	Path of the directory used to store the ISO backups. Ensure that this directory is large enough to store all the backups.
EXCLUDE_LIST	List of the directories and files to be saved in the backup. Choose only what seems important to save, in order to obtain a backup of a reasonable size.
BOOTARCH	Defines the architecture of the system to backup (x86, ia64, etc.). Check that the value fits the system.

The configuration can be performed using the Webmin interface:

<http://hostname:10000/mkcdrec/>

2.3.2 Creating a Backup

Perform these operations on the Management Node.

1. Log on as root user, in single mode.
2. Stop the activity on the Management Node; the ClusterDB must not be used during the backup operation.
3. Go to the **mkCDrec** base directory, by default this is `/var/opt/mkcdrec`:

```
cd /var/opt/mkcdrec
```

4. Check that the system is operational for **mkCDrec**:

```
make test
```

mkCDrec displays warning messages if it has detected that some elements are missing for the backup. If this happens, perform the appropriate corrections and restart **make test** until the test is successful.

5. Launch the backup operation:

```
make
```

A menu is displayed:

```
Enter your selection:
1) Create rescue CD-ROM only (no backups)
2) Create ISO backup images in /tmp
   (to burn on CDROM or DVD)
3) Create backup on disk
   (mounted harf disk, NFS mount point, SMB mount point)
4) Create backup on tape device /dev/nst0
5) Quit

Please choose from the above list [1-5]:
```

Select one of the displayed options (1 to 5).

Follow the instructions displayed on the screen.

When the operation is finished, ISO images ready for burning will be created in the directory specified in the configuration file (**CDREC_ISO_DIR** parameter).



Note: The **mkcdrec.log** file can be checked in case of problem.

Before burning a CD/DVD you can check the contents of the ISO image using the following command:

```
mount -o loop /backup/ISO/Cdrec.iso/mnt
```

2.3.3 Restoring a System

To restore a system, boot on the first CD-ROM/DVD-ROM, then run the command:

```
/etc/recovery/start-restore.sh
```

Follow the instructions displayed on the screen.

When the restore is completed, enter the **reboot** command. A new EFI boot entry is created.

2.4 Monitoring Maintenance Tools

2.4.1 Checking the status of InfiniBand Networks (ibstatus, ibstat)

2.4.1.1 ibstatus Command

ibstatus displays basic information obtained from each **InfiniBand** driver for the local adapter included in an **InfiniBand** network.

Normal output includes LID, Subnet Manager LID, port state (UP or DOWN), port physical state and the link width in terms of transfer rate. **-v** enable verbose mode which includes all **sysfs** supported parameters for the port interface and port.

Syntax:

```
ibstatus [-h] [devname[:port]]...
```

Examples:

- To display status of all IB ports, enter:

```
ibstatus
```

- To display status of mthca1 ports, enter:

```
ibstatus mthca1
```

- To show status of specified ports, enter:

```
ibstatus mthca1:1 mthca0:2
```

Output example for a mthca dual port HCA

Infiniband device 'mthca0' port 1 status:

```
default gid:      fe80:0000:0000:0000:0008:f104:0397:7ca5
base lid:         0x0
sm lid:          0x0
state:           1: DOWN
phys state:      2: Polling
rate:            2.5 Gb/sec (1X)
```

Infiniband device 'mthca0' port 2 status:

```
default gid:      fe80:0000:0000:0000:0008:f104:0397:7ca6
base lid:         0x2d
sm lid:          0x3
state:           4: ACTIVE
phys state:      5: LinkUp
rate:            10 Gb/sec (4X)
```


2.4.1.2 `ibstat` Command

`ibstat` works in a similar fashion to the `ibstatus` utility but is implemented as a binaries and not a script, and is more useful than `ibstatus` as more detailed information is provided. It includes options to list Channel Adapters and/or Ports.

Syntax:

```
ibstat [-d(efug) -l(list_of_cas) -p(orts_list) -s(hort)] <ca_name> [portnum]
```

`ibstat` command examples:

- To display status of all IB ports, enter:

```
ibstat
```

- To display status of `mt_hca1` ports, enter:

```
ibstat mt_hca1
```

- To show status of specified ports, enter:

```
ibstat mt_hca1 2
```

- To list the port GUIDs of `mt_hca0`, enter:

```
ibstat -p mt_hca0
```

- To list all CA names, enter:

```
ibstat -l
```

2.4.2 Diagnosing InfiniBand Fabric Problems (IBS tool)

This tool is used from the Management Node to diagnose problems for **InfiniBand** fabric using the cluster switch topology information contained in the **NetworkMap.xml** file, and the error checking counters contained in the **PortCounters.csv** file. Alternatively, an IBS database, **IBSDB**, containing all the switch information can be created and then used as the data source to diagnose the problems

Command syntax

```
ibs -a <action> [-hvcNE] [-l|-s <switch>] [-f <networkmap>] [-c <counters>]
```

The following options are available for the **ibs** command:

- h** Help file
- v** Verbose mode
- C** Disable colored text output
- a** Action (one of: **topo**, **bandwidth**, **errors**, **config**, **group**, **dbpopulate**, **availability**, **dbcreate**, **dbdelete**, **dbupdate**, **dbupdatepc**).

OFED related options

When working from the cluster Management Node, and provided this node is fitted with an **InfiniBand** adapter that is connected to an InfiniBand interconnect, it is recommended that the **-N** and **-E** options are used as the OFED software view of the cluster is more reliable than that provided by data taken directly from the switch.

- N** Query the IB subnet manager to obtain and update the hostname details.
- E** Query the IB subnet manager to obtain and update data using the error and traffic counters.

Data related options

By default IBS analyses the data contained in the IBSDB database unless the **-s** or **-l** flags are used. This default mode is known as 'database mode'.

- s <switch>** 'Connected mode'. Connect to the switch specified by its hostname or IP address and then retrieve the **NetworkMap.xml** and **PortCounters.csv** files for this switch.
- l** 'Local mode'. Use the **NetworkMap.xml** and **PortCounters.csv** files that are available locally or that are specified by the **-f** and **-c** flags for the analysis. These files can then be analysed separately on a machine which is not part of the cluster. However, as stated above it is better to work within the OFED stack using the **-N** and **-E** options to obtain the latest data.

- f filename** Specify the file to be used when loading or saving the network map file, **NetworkMap.xml**. When used in conjunction with the **-s switch** option, the file downloaded from the switch will be saved to file **<filename>**. When used in conjunction with the **-I** flag, the specified file will be used as the input file.
- c filename** Specify the file to be used when loading or saving the port counters file (**PortCounters.csv** file). When used in conjunction with the **-s** switch option, the file downloaded from the switch will be saved to the file **<filename>**. When used in conjunction with the **-I** flag, the specified file will be used as the input file.

2.4.2.1 IBS command actions

topo

The **topo** action for the **-a** option provides detailed topology details for the switch.

```
ibs -s <switch_name> -a topo -NE
```

This will give output that includes a description of the switches, the hostnames, the GUID for the Nodes, the LID for the Nodes, the physical location of the switches. The port details, including any errors, are shown in the bottom half of the screen for both local ports and for ports which are connected to remotely – see the screen example on the next page:

```

[localhost:~]# ibs -i swu0c0-0 -HE -a topo
Connecting to switch swu0c0-0
Done.
Sending request for file NetworkMap.xml
Done.
Getting response header from switch swu0c0-0
Done.
Downloading NetworkMap.xml
Done.
Creating IB hosts
Done.
Populating switch chassis with boards
No board found.
Assigned: 74, total: 74
Connecting ports
Done.
Populating network topology
Done.
Updating IP addresses from database clusterdb
Done.
Looking for program perfquery
Done.
Updating port counters using OFED perfquery
Done.
Assigning port counters
Done.
Connecting to database clusterdb on host localhost:5422
Done.
Updating equipment localisation from database clusterdb
Done.
Updating equipment IP addresses from database clusterdb
Done.
Updating switch IDs from database clusterdb
Done.
24 IP addresses updated.
21 switch IDs updated.

```

LOCAL										REMOTE									
PORT/PTN	PORTGUID	PORTNODEG	ERRORS	MODELID	SPEED	PORT	PIN	PORTGUID	PORTNODEG	TYPE	DESCRIPTION	HOSTNAME	MODELID	LOCATION	ERRORS				
2	0x0008f1040941254a			0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus2	0x0001	(A,1) RACK2/71					
3	0x0008f1040941254a			0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus2	0x0001	(A,1) RACK2/72					
4	0x0008f1040941254a			0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus2	0x0001	(A,1) RACK2/73					
5	0x0008f1040941254a			0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus2	0x0001	(A,1) RACK2/74					
6	0x0008f1040941254a			0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus2	0x0001	(A,1) RACK2/75					
7	0x0008f1040941254a		Linkdowned#1	0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus4	0x0013	(A,1) RACK2/76					
8	0x0008f1040941254a		Linkdowned#2	0x0001	4X 5.0 G	1	1	0x0002-9020024b5915	0x0002-9020024b5914	CA	MT25218 Infin.Hos	zeus5	0x0013	(A,1) RACK2/76					
9	0x0008f1040941254a			0x0001	4X 5.0 G	5	9	0x0002-9020024b5921	0x0002-9020024b5920	CA	MT25218 Infin.Hos	zeus0	0x0010	(A,1) RACK2/L	v115dr-opepd=2, xmdi-scard=1				
10	0x0008f1040941254a			0x0001	4X 5.0 G	10	10	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
11	0x0008f1040941254a			0x0001	4X 5.0 G	11	11	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
12	0x0008f1040941254a			0x0001	4X 5.0 G	12	12	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
13	0x0008f1040941254a			0x0001	4X 5.0 G	13	13	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
14	0x0008f1040941254a			0x0001	4X 5.0 G	14	14	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
15	0x0008f1040941254a			0x0001	4X 5.0 G	15	15	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
16	0x0008f1040941254a			0x0001	4X 5.0 G	16	16	0x0008f1040941254e	0x0008f1040941254e	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
17	0x0008f1040941254a			0x0001	4X 5.0 G	9	9	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0009	(A,2) RACK1/C					
18	0x0008f1040941254a			0x0001	4X 5.0 G	10	10	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
19	0x0008f1040941254a			0x0001	4X 5.0 G	11	11	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
20	0x0008f1040941254a			0x0001	4X 5.0 G	12	12	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
21	0x0008f1040941254a			0x0001	4X 5.0 G	13	13	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
22	0x0008f1040941254a			0x0001	4X 5.0 G	14	14	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
23	0x0008f1040941254a			0x0001	4X 5.0 G	15	15	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					
24	0x0008f1040941254a			0x0001	4X 5.0 G	16	16	0x0008f10409411946	0x0008f10409411946	Switch	IS90240 Voltaire	iswu0c-0	0x0008	(A,2) RACK1/B					

```

DESCRPTION | HOSTNAME | NODEGUID | MODELID | LOCATION
IS90240-M Voltaire | swu0c0-0 | 0x0008f1040941254a | 0x0001 | (A,2) RACK1/0

LOCAL
PORT/PTN | PORTGUID | PORTNODEG | ERRORS
1 | 0x0008f1040941254a | Linkdowned#6 |
2 | 0x0008f1040941254a | Linkdowned#1 |
3 | 0x0008f1040941254a |
4 | 0x0008f1040941254a |
5 | 0x0008f1040941254a |
6 | 0x0008f1040941254a | Linkdowned#4, Link recover=2,
7 | 0x0008f1040941254a | Linkdowned#3 |
8 | 0x0008f1040941254a | Linkdowned#5 |
9 | 0x0008f1040941254a |
10 | 0x0008f1040941254a |
11 | 0x0008f1040941254a |
12 | 0x0008f1040941254a |
13 | 0x0008f1040941254a |
14 | 0x0008f1040941254a |
15 | 0x0008f1040941254a |
16 | 0x0008f1040941254a |

REMOTE
PORT/PTN | PORTGUID | PORTNODEG | TYPE | DESCRIPTION | HOSTNAME | MODELID | LOCATION | ERRORS
1 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus8 | 0x0004 | (A,1) RACK2/ZC | v115dr-opepd=2, xmdi-scard=1
2 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus9 | 0x0003 | (A,1) RACK2/ZC | v115dr-opepd=2, xmdi-scard=1
3 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus11 | 0x0017 | (A,1) RACK2/ZB | xmdi-scard=2, v115dr-opepd=2
4 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus16 | 0x001D | (A,1) RACK2/G | xmdi-scard=2, v115dr-opepd=2
5 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus17 | 0x001E | (A,1) RACK2/G | xmdi-scard=2, v115dr-opepd=2
6 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus18 | 0x001E | (A,1) RACK2/F | xmdi-scard=11, v115dr-opepd=3, l
7 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus18 | 0x001E | (A,1) RACK2/F | xmdi-scard=11, v115dr-opepd=3, l
8 | 0x0002-9020024b5941 | 0x0002-9020024b5940 | CA | MT25218 Infin.Hos | zeus18 | 0x001E | (A,1) RACK2/F | xmdi-scard=11, v115dr-opepd=3, l
9 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
10 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
11 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
12 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
13 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
14 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
15 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |
16 | 0x0008f1040941254a | 0x0008f1040941254a | Switch | IS90240-M Voltaire | iswu0c-0 | 0x0001 | (A,2) RACK1/0 |

```

Figure 2-1. Example of IBS command topo action output

Use the command below to obtain the fabric topology using the data stored in the IBS database. The hostnames and traffic counters are updated using the OFED tools:

```
ibs -a topo -NE
```

Use the command below to dump the fabric topology using the local map file `test/NetworkMap.xml` and `test/portcounters.csv`. The data read from these files is updated using the OFED tools:

```
ibs -l -f test/NetworkMap.xml -c test/portcounters.csv -a topo -NE
```

bandwidth

The syntax for the bandwidth action is shown below. This action is very useful when benchmarking in order to monitor the performance of switch and to identify any bottlenecks.

```
ibs -s <switch_name> -a bandwidth -NE
```

Details of packets sent and received for the switch for both local and remote connections are displayed, as shown in Figure 2-2.

errors

The errors action can be used to produce a short report containing details of the faulty links for a switch. This is very useful for troubleshooting and will help to pinpoint any problems for the interconnects.

```
ibs -s <switch_name> -a errors -NE
```

This will give output, similar to that shown in Figure 2-3. **EPM** indicates the error rate in the form of Errors per Million packets sent.



See FAQ ID – F10040 “How to debug and clear InfiniBand fabric errors using FVM PM Counters CSV file?” available from www.voltaire.com for details of the different Port Counter error messages.


```

[localhost:~]# ibs -s iwu0c0-0 -vNE -s bandwidth
Done.
Connecting to switch iwu0c0-0
Sending request for file NetworkMap.xml
Getting response header from switch iwu0c0-0
Downloading NetworkMap.xml
Creating 18 hosts
Populating boards
Populating switch chassis with boards
Assigning ports to 18 hosts
Connecting to ports
Looking for program smquery
Updating hostnames using OFED smquery
Looking for program perfquery
Updating port counters using OFED perfquery
Assigning port counters
Connecting to database clusterdb on host localhost:5432
Updating equipment IP addresses from database clusterdb
Updating switch IP addresses from database clusterdb
Updating switch IDs from database clusterdb
Done.
No reallocations updated.
24 IP addresses updated.
21 switch IDs updated.
HCA: 21, ASICs: 0, ISRN024: 3, ISRN096: 0, ISRN288/301.2: 0, total: 24
boards: 0, chassis: 0
assigned: 0, total: 74
using /usr/local/ofed/bin/smquery
updated: 24, failed: 0, total: 24
using /usr/local/ofed/bin/perfquery
updated: 74, failed: 0, total: 74
assigned: 74, not assigned: 0, total: 74
Done.
No reallocations updated.
24 IP addresses updated.
21 switch IDs updated.
-----
DESCRPTION | HOSTNAME | MODELID | LOCATION |
-----
ISRN0240-M Voltair | iwu0c0-0 | 0x0008F104001254a | 0x0001 | (A,2) RACK1/D |
-----
REMARKS
-----
PORT/PIN | XMIT (MB) | RCY (MB) | XMIT PKT | RCY PKT | WIDTH | SPEED | ERRORS | LOCATION | ERRORS
-----
dropped=2 | 3 | 48 | 885635 | 680375 | 4X | 5.0 G | | (A,1) RACK2/Z | xmdt.scarid=2, vL15
4 | 266 | 18 | 123398 | 760752 | 4X | 5.0 G | | (A,1) RACK2/R |
5 | 4095 | 4095 | 8156285 | 6385244 | 4X | 5.0 G | | (A,1) RACK2/Z |
6 | 28 | 26 | 1093126 | 896361 | 4X | 5.0 G | Linkdowned=1 | (A,1) RACK2/O | vL15dr.opped=2, xmd
iscard=1 | 7 | 34 | 1093126 | 896361 | 4X | 5.0 G | | (A,1) RACK2/O | vL15dr.opped=2, xmd
8 | 4095 | 4095 | 103078847 | 85606653 | 4X | 5.0 G | Linkdowned=2 | (A,1) RACK2/L | vL15dr.opped=2, xmd
iscard=1 | 9 | 4095 | 4294967295 | 3824691544 | 4X | 5.0 G | | (A,2) RACK1/C |
10 | 4095 | 4095 | 3464915143 | 4294967295 | 4X | 5.0 G | | (A,2) RACK1/C |
11 | 4095 | 4095 | 93470532 | 11435618 | 4X | 5.0 G | | (A,2) RACK1/C |
12 | 4095 | 4095 | 504124256 | 44788 | 4X | 5.0 G | | (A,2) RACK1/C |
13 | 4095 | 4095 | 504124256 | 44788 | 4X | 5.0 G | | (A,2) RACK1/C |
14 | 4095 | 47 | 283250610 | 1354886 | 4X | 5.0 G | | (A,2) RACK1/C |
15 | 4095 | 7 | 26033 | 4294967295 | 4X | 5.0 G | | (A,2) RACK1/C |
16 | 4095 | 4095 | 465606020 | 2843232505 | 4X | 5.0 G | | (A,2) RACK1/C |
17 | 4095 | 4095 | 4294967295 | 4294967295 | 4X | 5.0 G | | (A,2) RACK1/B |
18 | 4095 | 259 | 557579423 | 964474 | 4X | 5.0 G | | (A,2) RACK1/B |
19 | 4095 | 4095 | 62246288 | 12522285 | 4X | 5.0 G | | (A,2) RACK1/B |
20 | 4095 | 8 | 6326288 | 55522285 | 4X | 5.0 G | | (A,2) RACK1/B |
21 | 4095 | 8 | 135771 | 50740 | 4X | 5.0 G | | (A,2) RACK1/B |
22 | 4095 | 4095 | 4294967295 | 3464843853 | 4X | 5.0 G | | (A,2) RACK1/B |
23 | 4095 | 4095 | 3152923600 | 65977482 | 4X | 5.0 G | | (A,2) RACK1/B |
24 | 4095 | 4095 | 382506053 | 2743468922 | 4X | 5.0 G | | (A,2) RACK1/B |
-----

```

Figure 2-2. Example of IBS command bandwidth action output

```

[root@zeus2 ~]# ibs -s lsu0c0-0 -vME -a errors
Connecting to switch lsu0c0-0
Sending request for file NetworkMap.xml
Getting response header from switch lsu0c0-0
Downloading NetworkMap.xml
Creating IB hosts
Populating boards
Assigning ports to IB hosts
Connecting ports
Looking for program smquery
Updating hostnames using OFED smquery
Updating port counters using OFED perquery
Assigning port counters
Updating equipment localisation from database clusterdb
Updating equipment IP addresses from database clusterdb
Updating switch IDs from database clusterdb

```

HOSTNAME	PORT	PTN	LID	LOCATION	EPM	REMOTE_HOSTNAME	PORT	PTN	LID	REMOTE_LOCATION	EPM	ERRORS
zeus19	1	1	0x0013	(A,1) RACK2/F	0.333	lsu0c0-1	8	8	0x0018	(A,2) RACK1/C	0.000	xmcdscard=1
zeus5	1	1	0x0008	(A,1) RACK2/L	0.384	lsu0c0-1	8	8	0x0018	(A,2) RACK1/C	3.5	xmcdscard=12,v115dr-opped=2,linkdowned=1
zeus20	1	1	0x0011	(A,1) RACK2/E	0.000	lsu0c0-2	5	3	0x0017	(A,2) RACK1/B	0.000	xmcdscard=4,v115dr-opped=2
zeus14	1	1	0x0006	(A,1) RACK2/Y	0.000	lsu0c0-2	3	3	0x0017	(A,2) RACK1/B	0	xmcdscard=3
zeus9	1	1	0x0005	(A,1) RACK2/Z	0.375	lsu0c0-2	2	2	0x0018	(A,2) RACK1/C	0.000	xmcdscard=4,v115dr-opped=2
zeus22	1	1	0x0015	(A,1) RACK2/C	0.6	lsu0c0-2	7	7	0x0017	(A,2) RACK1/B	0.000	rcover=2,xmcdscard=1
lsu0c0-0	11	11	0x0001	(A,2) RACK1/D	0.002	lsu0c0-1	11	11	0x0018	(A,2) RACK1/C	0	xmcdscard=1
lsu0c0-0	21	21	0x0001	(A,2) RACK1/D	0.004	lsu0c0-2	13	13	0x0017	(A,2) RACK1/B	0.079	xmcdscard=1
lsu0c0-0	7	7	0x0001	(A,2) RACK1/D	4	zeus4	1	1	0x0008	(A,1) RACK2/O	0.522	xmcdscard=6,linkrecovery=1,linkdowned=1
lsu0c0-0	17	17	0x0001	(A,2) RACK1/D	0.019	lsu0c0-2	9	9	0x0017	(A,2) RACK1/B	0	xmcdscard=2,linkdowned=1
lsu0c0-0	22	22	0x0001	(A,2) RACK1/D	0.046	lsu0c0-2	14	14	0x0017	(A,2) RACK1/B	0	xmcdscard=2,linkdowned=1
lsu0c0-0	18	18	0x0001	(A,2) RACK1/D	0.034	lsu0c0-2	10	10	0x0017	(A,2) RACK1/B	0	xmcdscard=2,linkdowned=1
lsu0c0-0	23	23	0x0001	(A,2) RACK1/D	0.010	lsu0c0-2	15	15	0x0017	(A,2) RACK1/B	0	xmcdscard=2,linkdowned=1
lsu0c0-0	16	16	0x0001	(A,2) RACK1/D	0.041	lsu0c0-1	16	16	0x0018	(A,2) RACK1/C	0	xmcdscard=2,linkdowned=1
lsu0c0-0	13	13	0x0001	(A,2) RACK1/D	0.012	lsu0c0-1	13	13	0x0018	(A,2) RACK1/C	0	xmcdscard=2,linkdowned=1
lsu0c0-0	6	6	0x0001	(A,2) RACK1/D	12	zeus6	1	3	0x0012	(A,1) RACK2/ZH	4	linkdowned=6,xmcdscard=5,linkrecovery=1
lsu0c0-0	3	3	0x0001	(A,2) RACK1/D	0.13	lsu0c0-1	12	2	0x0018	(A,2) RACK1/C	0.002	xmcdscard=1
lsu0c0-0	20	20	0x0001	(A,2) RACK1/D	0.013	lsu0c0-2	12	2	0x0017	(A,2) RACK1/B	0	xmcdscard=2,linkdowned=1
lsu0c0-0	14	14	0x0001	(A,2) RACK1/D	0.041	lsu0c0-1	12	11	0x0018	(A,2) RACK1/C	0	xmcdscard=2,linkdowned=1
lsu0c0-0	15	15	0x0001	(A,2) RACK1/D	N/A	zeus7	15	15	0x0018	(A,2) RACK1/C	0.384	xmcdscard=5,linkrecovery=1,linkdowned=1
lsu0c0-0	8	8	0x0001	(A,2) RACK1/D	3.5	zeus7	1	1	0x0008	(A,1) RACK2/R	8	xmcdscard=6,linkdowned=1
lsu0c0-0	4	4	0x0001	(A,2) RACK1/D	7	zeus7	1	1	0x000E	(A,1) RACK2/R	0.000	xmcdscard=1,linkdowned=1
lsu0c0-0	24	24	0x0001	(A,2) RACK1/D	N/A	lsu0c0-2	16	16	0x0017	(A,2) RACK1/B	0	xmcdscard=1,linkdowned=1
lsu0c0-0	10	10	0x0001	(A,2) RACK1/D	N/A	lsu0c0-2	10	10	0x0018	(A,2) RACK1/B	0.000	xmcdscard=1,linkdowned=1
lsu0c0-0	19	19	0x0001	(A,2) RACK1/D	N/A	lsu0c0-2	11	11	0x0017	(A,2) RACK1/B	0.000	xmcdscard=1,linkdowned=1
lsu0c0-0	5	5	0x0001	(A,2) RACK1/D	8	zeus3	1	1	0x0003	(A,1) RACK2/Z	0.001	xmcdscard=6,linkrecovery=1,linkdowned=1
zeus21	1	1	0x000C	(A,1) RACK2/O	0.000	lsu0c0-2	6	6	0x0017	(A,2) RACK1/B	0.000	xmcdscard=11,linkdowned=1
zeus2	1	1	0x0003	(A,1) RACK2/Z	0.001	lsu0c0-2	5	5	0x0001	(A,2) RACK1/B	0.000	xmcdscard=11,linkdowned=1
zeus23	1	1	0x0016	(A,1) RACK2/B	0.2	lsu0c0-2	8	8	0x0017	(A,2) RACK1/B	0.000	xmcdscard=7,v115dr-opped=2
zeus12	1	1	0x000A	(A,1) RACK2/A	0.5	lsu0c0-2	1	1	0x0017	(A,2) RACK1/B	0	xmcdscard=2,v115dr-opped=2
zeus13	1	1	0x000A	(A,1) RACK2/Z	0.375	lsu0c0-2	2	2	0x0017	(A,2) RACK1/B	0.001	xmcdscard=4,v115dr-opped=2
zeus8	1	1	0x0012	(A,1) RACK2/ZH	4	lsu0c0-1	6	6	0x0018	(A,2) RACK1/C	0	xmcdscard=15,v115dr-opped=4,linkdowned=1
zeus2	1	1	0x0009	(A,1) RACK2/Z	0.125	lsu0c0-0	3	3	0x0001	(A,2) RACK1/D	7	xmcdscard=13,v115dr-opped=2,linkdowned=1
zeus7	1	1	0x000F	(A,1) RACK2/R	8	lsu0c0-0	5	5	0x0018	(A,2) RACK1/C	0	xmcdscard=5,v115dr-opped=2
zeus16	1	1	0x000E	(A,1) RACK2/G	0.000	lsu0c0-1	6	6	0x0018	(A,2) RACK1/C	0.000	linkdowned=4,linkrecovery=2,linkdowned=2,linkrecovery=1
zeus17	6	6	0x0018	(A,2) RACK1/C	0.002	zeus17	1	1	0x0014	(A,1) RACK2/F	0.333	linkdowned=4,linkrecovery=2,xmcdscard=1
lsu0c0-1	7	7	0x0018	(A,2) RACK1/C	0.000	zeus18	1	1	0x0014	(A,1) RACK2/F	0.1	linkdowned=5
lsu0c0-1	9	9	0x0018	(A,2) RACK1/C	0.000	zeus18	9	9	0x0001	(A,2) RACK1/D	0.375	xmcdscard=20
lsu0c0-1	8	8	0x0018	(A,2) RACK1/C	0.000	zeus19	1	1	0x0005	(A,1) RACK2/Z	0.333	linkdowned=1
lsu0c0-1	1	1	0x0018	(A,2) RACK1/C	0.000	zeus19	1	1	0x0003	(A,1) RACK2/Z	0.375	linkdowned=7
zeus18	1	1	0x0014	(A,1) RACK2/F	0.001	zeus8	7	7	0x0005	(A,1) RACK2/F	0.375	linkdowned=6
lsu0c0-2	1	1	0x0014	(A,1) RACK2/F	0.333	lsu0c0-1	1	1	0x0018	(A,2) RACK1/C	0.001	linkdowned=1
lsu0c0-2	7	7	0x0017	(A,2) RACK1/B	0.000	lsu0c0-0	19	19	0x0015	(A,2) RACK1/C	N/A	linkdowned=1
lsu0c0-2	11	11	0x0017	(A,2) RACK1/B	0.000	lsu0c0-0	1	1	0x0015	(A,2) RACK1/C	N/A	linkdowned=7
lsu0c0-2	16	16	0x0017	(A,2) RACK1/B	0.000	lsu0c0-0	24	24	0x0001	(A,2) RACK1/D	N/A	linkdowned=1
lsu0c0-2	13	13	0x0017	(A,2) RACK1/B	0.079	lsu0c0-0	21	21	0x0001	(A,2) RACK1/D	0.004	xmcdscard=22
lsu0c0-2	6	6	0x0017	(A,2) RACK1/B	0.000	zeus21	1	1	0x000C	(A,1) RACK2/O	0.000	linkdowned=1
lsu0c0-2	8	8	0x0017	(A,2) RACK1/B	0.000	zeus23	1	1	0x0015	(A,2) RACK1/B	0.2	linkdowned=5
lsu0c0-2	5	5	0x0017	(A,2) RACK1/B	0.000	zeus20	1	1	0x0015	(A,2) RACK1/B	0.000	linkdowned=2
zeus4	1	1	0x0008	(A,1) RACK2/O	0.522	lsu0c0-0	7	7	0x0001	(A,1) RACK2/E	0.000	xmcdscard=20,v115dr-opped=2,linkdowned=1
zeus15	1	1	0x0002	(A,1) RACK2/X	0.000	lsu0c0-2	4	4	0x0017	(A,2) RACK1/B	4	xmcdscard=3
zeus11	1	1	0x0004	(A,1) RACK2/ZB	0.000	lsu0c0-1	4	4	0x0018	(A,2) RACK1/C	0	xmcdscard=5,v115dr-opped=2

```

[root@zeus2 ~]#

```

Figure 2-3. Example of IBS command errors action output

config

This action manually creates the instruction sequence needed to configure the hostname mapping for a switch.



Note: This option only applies to Voltaire switches which use 4.0 or later firmware versions.

```
ibs -s <switch_name> -vNE -a config
```

group

This action generates the **group.csv** file that includes the hostname mapping configuration details for all the switches, this can then be imported into a switch in order to configure it. For large clusters, this is quicker than running the **config** action (as detailed above), to generate and import the cluster switch configuration details into a switch.



Note: This option only applies to **Voltaire** switches which use version 4.0 or later firmware.

```
ibs -s iswu0c0-0 -a group
```

While the command is being carried out a message similar to that below will appear:

```
Successfully generated configuration file group.csv
To update a managed switch, proceed as follows:
- Log onto the switch
- Enter the 'enable' mode
- Enter the 'config' menu
- Enter the 'group' menu
- Type the following command: group import /home/user/path
```

2.4.2.2

IBSDB Database

It is possible to create a database, which includes all the hardware and InfiniBand traffic details for all the switches, with the **IBS** tool. This database is specific to **InfiniBand** hardware.

The following commands apply to the **IBSDB** Database.

dbcreate

To create an empty, new IBS database (ibsdbs) use the **dbcreate** command. Only the **'postgres'** user is allowed to create an empty database.

```
postgres@admin$ ibs -a dbcreate
```


While the command is being carried out a message similar to that below will appear:

```
-----  
Looking for program createdb                using /usr/bin/createdb  
Looking for program psql                    using /usr/bin/psql  
Creating database ibsdb                     Done.  
Loading table definitions into database ibsdb Done.  
-----
```

dbdelete

To delete an IBS database (ibsdB) use the **dbdelete** command. Only the 'postgres' user is allowed to delete an empty database.

```
postgres@admin$ ibs -a dbdelete
```

While the command is being carried out a message similar to that below will appear:

```
-----  
Looking for program dropdb                  using /usr/bin/dropdb  
Deleting database ibsdb                     Done.  
-----
```

dbpopulate

Use the **dbpopulate** action to populate a new database. In the example below data is supplied from the **iswu0c0-0** managed switch from the Management Node, and the hostnames and traffic counters are populated using the OFED tools:

```
ibs -s iswu0c0-0 -a dbpopulate -vNE
```

While the command is being carried out a message similar to that below will appear:

```
-----  
Connecting to switch iswu0c0-0              Done.  
Sending request for file NetworkMap.xml     Done.  
Getting response header from switch iswu0c0-0 Done.  
Downloading NetworkMap.xml  
Creating IB hosts   HCA: 21, ASICS: 0, ISR9024: 3, ISR9096: 0, ISR9288/2012: 0, total: 24  
Populating boards                                     No board found.  
Populating switch chassis with boards            boards: 0, chassis: 0  
Assigning ports to IB hosts                      assigned: 74, total: 74  
Connecting ports                                  assigned: 37 pairs, total: 37 pairs.  
Looking for program smpquery                    using /usr/local/ofed/bin/smpquery  
Updating hostnames using OFED smpquery          updated: 24, failed: 0, total: 24  
Looking for program perfquery                   using /usr/local/ofed/bin/perfquery  
Updating port counters using OFED perfquery     updated: 74, failed: 0, total: 74  
Assigning portcounters                          assigned: 74, not assigned: 0, total: 74  
Connecting to database clusterdb on host localhost:5432 Done.  
Updating equipment localisation from database clusterdb 24 localisations updated.  
Updating equipment IP addresses from database clusterdb 24 IP addresses updated.  
Updating switch IDs from database clusterdb       21 switch IDs updated.  
Connecting to database ibsdb on host localhost:5432 Done.  
-----
```

Populating table 'chassis' in database ibsdb	0 chassis stored.
Populating tables 'asic' and 'chassis' in database ibsdb	3 ISR9024 switch stored.
Populating table 'board' in database ibsdb	0 boards stored.
Populating table 'asic' in database ibsdb	0 ASICs stored.
Populating table 'hca' in database ibsdb	21 HCAs stored.
Populating tables 'asic_port' and 'hca_port' in database ibsdb	74 ports stored.
Populating tables 'asic_portcounters' and 'hca_portcounters'	74 portcounters stored.

dbupdate

Use the **dbupdate** action to update an existing IBSDb database.

In the example below the topology and traffic counter details for the **iswu0c0-0** managed switch from the Management Node, is updated using the OFED tools:

```
ibs -s iswu0c0-0 -a dbupdate -NE
```

In order to ensure that the data is always up to date, add the following line to the **cron** table (using **crontab -e**).

```
*/10 * * * * PATH=/usr/local/ofed/bin:$PATH /usr/bin/ibs -s  
iswu0c0-0 -a dbupdate -vNE >> /var/log/ibs.log 2>&1
```

The traffic and error counters as well as the **InfiniBand** equipment stored in the **IBS** database will be refreshed every 10 minutes using the data supplied by the **iswu0c0-0** switch



Note:

The user needs to know which switch is running the subnet manager as master for **InfiniBand** clusters that include multiple managed switches. This switch should always be the one that is specified as the argument of the **-s** flag. Assuming that the data is refreshed by the **cron** daemon, then if another switch becomes the subnet manager master the data details contained in the database would then be incorrect, as it would use data from what is the slave switch as defined in the cron script.

Use the **sminfo** command as follows to know which subnet manager is running as the master:

Output in a form similar to that below will be provided:

```
-----  
sminfo: sm lid 1 sm guid 0x8f1040041254a, activity count 544113 priority  
3 state 3 SMINFO_MASTER  
-----
```

The **guid** that is identified can then be used to find the corresponding switch name in the ibsdb 'chassis' table.

dbupdatepc

Use the **dbupdatepc** action to update the port counters for an existing IBSDb database. Use the command below:

```
ibs -a dbupdatepc -vNE
```

availability

Use the **availability** action to see which ports and links are available for the **InfiniBand** interconnects. This action will not work unless the IBSDb database has been created and populated.

```
ibs -s iswu0c0-0 -a availability
```

This will give results in a similar format to that below.

```
-----  
Active ports: 74  
Active uplinks: 16  
Active downlinks: 21  
-----
```

2.4.2.3

Return Values

IBS returns 0 for success. Any other value indicates a failure.

2.4.3 Monitoring Voltaire Switches (switchname)

Different options exist for monitoring and maintaining the performance of **Voltaire** switches.

To begin with enter the utilities menu as follows:

```
[user@host ~]# ssh enable@switchname
```

```
-----  
enable@switchname's password: voltaire  
Welcome to Voltaire Switch switchname  
Connecting  
-----
```

```
switchname # utilities  
switchname (utilities)#
```

2.4.3.1 Resetting the counters

The counters (volume and errors) can be reset through the **zero-counters** command as follows:

```
switchname (utilities) zero-counters
```

```
Zero All Counters  
Zero lid 8 port 255 mask 0xffff  
[ ... ]
```

2.4.3.2 Finding bad ports

The **find_bad_ports** command can be used to detect faulty ports:

```
switchname (utilities) find_bad_ports
```

```
-----  
Found bad link/port:  
node_guid:.....0008f10400411946  
node_desc:.....'ISR9024D Voltaire'  
lid:.....152  
smlid:.....8  
Port 4  
direct path from self switch: 0,1 4  
-----
```

2.4.3.3 Verifying the ports

The whole Infiniband fabric can be checked using the **port-verify** command as follows:

```
switchname (utilities) port-verify
```

```
#
# Topology file: generated on Thu Oct  4 20:19:24 2007
#
devid=0x5a31
switchguids=0x8f1040041254a
Switch 24 "S-0008f1040041254a" # "ISR9024D-M Voltaire" smalid 8
[1] "S-0008f10400411946"[13] width 4X speed 5.0 Gbs
[2] "S-0008f10400411946"[14] width 4X speed 5.0 Gbs
[3] "S-0008f10400411946"[15] width 4X speed 5.0 Gbs
[ ... ]
devid=0x6282
hcaguids=0x2c9020024b940
Hca 2 "H-0002c9020024b940" # "zeus8 HCA-1"
[1] "S-0008f1040041281e"[1] # lid 72 lmc 3 width 4X speed 5.0 Gbs
SUMMARY: NO PROBLEMS DETECTED.
```

2.4.3.4 Checking the port width

To ensure the best performance, check that the ports are running in 4x mode as follows:

```
switchname (utilities) width-check
```

```
Verify / every error found - will be printed
lid 8 guid 0008f1040041254a ports 24
lid 160 guid 0008f1040041281e ports 24
lid 152 guid 0008f10400411946 ports 24
```

2.4.3.5 Dealing with a faulty port

When a faulty port is diagnosed, it can be disabled or reset using the **port-manage** command, as below:

```
iswu0c0-0(utilities) port-manage
```

Description:

port-manage.sh is used to trigger a physical state change for the port specified. This is useful when the active width/speed of a specific port must be changed without the cable being reconnected.

Syntax:

```
port-manage.sh [-v] [-f] <-d|-e|-r> <LID> <PORT>
```

Options:

- v** Increase output verbosity level
- f** Force disabling or resetting a port even when the port is located on the Access Path (path/way to the specific port)
- d lid port** Disable the port
- e lid port** Enable the port (set port state machine to polling state)
- r lid port** Reset the port
- S lid port** Reset the port and set Enabled Speed to SDR
- D lid port** Reset the port and set Enabled Speed to SDR/DDR
- h** Show this help

Example:

```
#port-manage.sh -r 17 21 (reset LID=17 PORT=21)
```

2.4.4 Getting Information about Storage Devices (lsioctg)

lsioctg is a tool used for reporting information about storage devices. It is mainly dedicated to external storage systems (DDN and FDA disk arrays) and their dedicated Host Board Adapters (Emulex FC adapters), but it can also be used with internal system storage (system disks) and their Host Board Adapters tools.

Reported information is related to several inventories:

- Host Board Adapters (-c flag)
- Disks (-d flag)
- Disk partitions (-p flag)
- Disk usages.

Syntax:

According to needed information, **lsioctg** can be used with options related to each inventory.

- **lsioctg [-P] [-v] -c [HBAs IDs]**
Gives information about all SCSI controllers. If HBAs IDs are specified, only applies to this list of HBAs.
- **lsioctg [-P] [-v] -d [-u] [devices names]**
Gives information about SCSI devices. [-u] has to be used to display non disk devices. If devices are specified, only applies to this list of devices.
- **lsioctg -p**
Displays partitions.
- **lsioctg [-P] [-v] -a**
Dsplays all (= -cdp).
- **lsioctg [-r user] -n remote node [-P] [-v] [-c|-d|-a]**
Gives information from remote node about controllers/disks.
- **lsioctg -M [devices names]**
Gives information about SCSI devices usage.
- **lsioctg <-l|-L> <wwpn>**
Reports WWPN owner. The -l flag uses `/etc/wwn` file, and the -L flag uses cluster manager database.
- **lsioctg <-w|-W>**
Displays all WWPN owners. The -w flag uses `/etc/wwn` file, and the -W flag uses cluster manager database.

General flags:

- P No headers (before -[a|c|d] commands).
- v Verbose (before -[a|c|d] commands). WWPN verbose information is extracted from `/etc/wwn` file.

- h Help message. Exclusive with other options.
- V Display the version. Exclusive with other options.

Online help and a man page give information about **lsiocfg** usage.

2.4.4.1 HBA Inventory

Using the **lsiocfg** HBA inventory option, you can get basic information about Host Board Adapters:

- model,
- link up or down.

When getting HBA inventory in verbose mode, more details are available:

- firmware levels,
- serial number,
- WWNN and WWPN (for fibre channel HBAs).

Example:

```
# lsiocfg -cv

-----
----- HOST/CHANNEL INVENTORY -----
Host  Driver      Unique_id  Cmd/Lun  HostQ  State      Model
-----
host0  mptbase      0          7        -      -          -
host1  mptbase      1          7        -      -          -
host2  lpfc         0          30       -      LINK_UP    LP11000
      DRV=8.0.30_p1
      FW=2.10A7 (B2D2.10A7)
      Bus-Number=26
      SN=VM53824841
      Host-WWNN=20:00:00:00:c9:4b:e7:02
      Host-WWPN=10:00:00:00:c9:4b:e7:02
      FN=20:00:00:00:c9:4b:e7:02
      speed=2 Gbit
host3  usb-storage  0          1        -      -          -
-----
```

2.4.4.2 Disks Inventory

Using the **lsiocfg** Disk inventory option, you can get basic information about the available disks:

- system location
- vendor
- state
- disk size.

When getting the disk inventory in verbose mode, more details are shown:

- model
- serial number

- firmware revision
- WWPN (fiber channel devices).

```
# lsiocfg -dv
```

```
----- DISK INVENTORY -----
Dev  Location  Maj:Min  Vendor      state  Size (MB) QueueDepth Lname
(location= Host:Channel:Id:LUN)
-----
```

Dev	Location	Maj:Min	Vendor	state	Size (MB)	QueueDepth	Lname
sdb	0:0:10:0	8:16	SEAGATE	running	286102	31	
	MODEL=SEAGATE ST3300007LC FWREV=0003 SERIAL=3KR0KTPH00007547TR0P TRANSPORT=SPI						
sdc	0:0:11:0	8:32	SEAGATE	running	286102	31	
	MODEL=SEAGATE ST3300007LC FWREV=0003 SERIAL=3KR0KTHM000075475NWC TRANSPORT=SPI						
sda	0:0:9:0	8:0	SEAGATE	running	286102	31	
	MODEL=SEAGATE ST3300007LC FWREV=0003 SERIAL=3KR0JT0T00007548GUXA TRANSPORT=SPI						
sdd	2:0:0:0	8:48	DDN	running	10000	30	/dev/ldn.ddn0.13
	MODEL=DDN S2A 8500 FWREV=5.20 SERIAL=02A820510D00 TRANSPORT=FC WWPN=24:00:00:01:ff:03:02:a8 NAME=unknown						
sde	2:0:0:1	8:64	DDN	running	125000	30	/dev/ldn.ddn0.14
	MODEL=DDN S2A 8500 FWREV=5.20 SERIAL=02A820540E00 TRANSPORT=FC WWPN=24:00:00:01:ff:03:02:a8 NAME=unknown						
sdf	2:0:0:2	8:80	DDN	running	10000	30	/dev/ldn.ddn0.15
	MODEL=DDN S2A 8500 FWREV=5.20 SERIAL=03E020570F00 TRANSPORT=FC WWPN=24:00:00:01:ff:03:02:a8 NAME=unknown						
sdg	2:0:0:3	8:96	DDN	running	125000	30	/dev/ldn.ddn0.16
	MODEL=DDN S2A 8500 FWREV=5.20 SERIAL=03E0205A1000 TRANSPORT=FC WWPN=24:00:00:01:ff:03:02:a8 NAME=unknown						

```
-----
```

2.4.4.3 Disk Usage and Partition Inventories

These inventories give information about system and logical use of the devices. Such information is mostly used for system administration needs.

2.4.5 Checking Device Power State (pingcheck)

The **pingcheck** command checks the power state (on or off) of the specified devices.

Usage:

```
pingcheck [options] --Type <device type> command devices
```

Options:

- dbname name** Specify database name.
- debug, -d** Debug mode (more than verbose).
- help, -h** Display **pingcheck** help.
- interval, -i** Specify the number of nsm calls before waiting the period defined by the **--time** option.
- jobs, -j** Number of simultaneous nsm actions (for example, with -j 5 you can run 5 simultaneous **nsmpower** processes). Default: 30.
- only_test, -o** Display the NS Commands that would be launched according to the specified options and action. This is a testing mode, no action is performed.
- time, -t** Time to wait after the number of nsm calls defined by the **--interval** option.
- verbose, -v** Verbose mode.

Parameters

- Type <device type>** Type of devices to be «pinged»: **disk_array** or **server**.
- command** **on** or **off**.
- devices** Specify the name of the devices, using the **basename[i,j-k]** or **lc-like** syntax.

Examples:

- The following command verifies that all the power supplies for **disk_array** 10 to 15 are in **on** state and indicates those which are not.

```
pingcheck --Type disk_array on da[10-15]
```

- The following command verifies that servers **nova**5 to 7 are in **off** state and indicates those which are not.

```
pingcheck --Type server off nova[5-7]
```

2.5 Debugging Maintenance Tools

2.5.1 Modifying the Core Dump Size

By default the maximum size for core dump files for Bull HPC systems is set to 0 which means that no resources are available and core dumps cannot be done. In order that core dumps can be done the values for the **ulimit** command have to be changed.

For more information refer to the options for the **ulimit** command in the **bash** man page.

2.5.2 Identifying InfiniBand Network Problems (**ibdoctor**, **ibtracert**)

ibdoctor is Bull tool, which calls on the **ibtracert**, **ibnetdiscover**, and **smpquery** diagnostic tools, whilst at the same time interfacing with the **ClusterDB** database so that any problems in the **InfiniBand** network can be identified easily.

2.5.2.1 **ibdoctor** Command

ibdoctor may be used:

- to identify where any problem adapters or nodes are located
- to display communication paths, including bandwidth, between ports in a human readable format.

Options:

- s <src_lid>** Use specified source lid.
- d <dst_lid>** Use specified destination lid.
- t** Trace route between **<src_lid>** and **<dst_lid>**.
- T** Report the fabric state over all known routes.
- h** Help.

Example:

- To display status data for the path between two **InfiniBand** adapters with the local identifiers **0x14** and **0x1e**, enter:

```
ibdoctor -t -s 0x14 -d 0x1e
```

The output looks as follows:

OUT	balis4 HCA-1	RACK2 M	lid 0x14	port 1	guid 0002c90200234144	state Active	width 4X	rate 5.0 Gbps
INTO	ISR9024D Voltaire		lid 0x11	port 2	guid 0008f10400411da2	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D Voltaire		lid 0x11	port12	guid 0008f10400411da2	state Active	width 4X	rate 5.0 Gbps
INTO	balis23 HCA-1	RACK2 K	lid 0x1e	port 1	guid 0002c902002341b1	state Active	width 4X	rate 5.0 Gbps

- The **-T** option completes an exhaustive scan of the network, and traces and checks all the possible routes between the adapters:

```
ibdoctor -T
```

The output looks as follows:

28 lids found

OUT	ISR9024D-M Voltaire		lid 0x1	port 0	guid 0008f10400411e54	state Active	width 4X	rate 2.5 Gbps
INTO	ISR9024D Voltaire		lid 0x2	port 15	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D-M Voltaire		lid 0x1	port 0	guid 0008f10400411e54	state Active	width 4X	rate 2.5 Gbps
INTO	ISR9024D Voltaire		lid 0x11	port 13	guid 0008f10400411da2	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D Voltaire		lid 0x11	port 18	guid 0008f10400411da2	state Active	width 4X	rate 5.0 Gbps
INTO	ISR9024D Voltaire		lid 0x3	port 6	guid 0008f10400411d70	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D-M Voltaire		lid 0x1	port 0	guid 0008f10400411e54	state Active	width 4X	rate 2.5 Gbps
INTO	ISR9024D Voltaire		lid 0x2	port 15	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D Voltaire		lid 0x2	port 4	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
INTO	bali6 HCA-1	RACK1 D	lid 0x4	port 1	guid 0002c90200234405	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D-M Voltaire		lid 0x1	port 0	guid 0008f10400411e54	state Active	width 4X	rate 2.5 Gbps
INTO	ISR9024D Voltaire		lid 0x2	port 16	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D Voltaire		lid 0x2	port 5	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
INTO	bali7 HCA-1	RACK1 E	lid 0x5	port 1	guid 0002c9020023440d	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D-M Voltaire		lid 0x1	port 0	guid 0008f10400411e54	state Active	width 4X	rate 2.5 Gbps
INTO	ISR9024D Voltaire		lid 0x2	port 3	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps
OUT	ISR9024D Voltaire		lid 0x2	port 6	guid 0008f10400411d6a	state Active	width 4X	rate 5.0 Gbps

2.5.2.2 ibtracert Command

ibtracert uses Subnet Manager Protocols (**SMP**) to trace the path from a source GID/LID to a destination GID/LID. Each hop along the path is displayed until the destination is reached or a hop does not respond. By using the **-mg** and/or **-ml** options, multicast path tracing can be performed between the source and destination nodes.

Syntax:

```
ibtracert [options] <src-addr> <dest-addr>
```

Flags

- n** Simple format; no additional information is displayed.
- m <mlid>** Show the multicast trace of the specified mlid.

Examples

- To show trace between lid 2 and 23, enter:

```
ibtracert 2 23
```

- To show multicast trace between lid 3 and 5 for mcast lid 0xc000, enter:

```
ibtracert -m 0xc000 3 5
```

Output:

The output for a command between two points is displayed in both hexadecimal format and in human-readable format – as shown in the example below for the trace between the two lids 0x22 and 0x2c. This is very useful in helping to identify any port/switch problems in the **InfiniBand** Fabric.

```
ibtracert 0x22 0x2c
```

```
-----  
>From ca {0008f10403979958} portnum 1 lid 0x22-0x22 "lynx13 HCA-1"  
[1] -> switch port {0008f104004118e2}[8] lid 0x4-0x4 "ISR9024D Voltaire"  
[13] -> switch port {0008f104004118e8}[16] lid 0x3-0x3 "ISR9024D-M Voltaire"  
[21] -> switch port {0008f104004118e4}[13] lid 0x1-0x1 "ISR9024D Voltaire"  
[4] -> ca port {0008f10403979985}[1] lid 0x2c-0x2c "lynx19 HCA-1"  
To ca {0008f10403979984} portnum 1 lid 0x2c-0x2c "lynx19 HCA-1"
```

In short:

```
=> OUT lynx13 (lid 0x22 / port 1  
=> INTO node switch (lid 0x4) / port 8  
=> OUT node switch (lid 0x4) / port 13  
=> INTO top switch (lid 0x3) / port 16  
=> OUT top switch (lid 0x3) / port 21  
=> INTO node switch (lid 0x1) / port 13  
=> OUT node switch (lid 0x1) / port 4  
=> INTO lynx 19 (lid 0x2c) / port 1  
-----
```

2.5.3 Using dump tools with RHEL5 (crash, proc, kdump)

Various tools allow problems to be analysed whilst the system is in operation:

- **crash** portrays system data symbolically using the possibilities provided by the **GDB** debugger. The commands which it offers are system oriented, for example, the list of tasks, tracing function calls for a task which is waiting, etc.
See the **crash** man page for more information.
- The system file **/proc** may be used to view, and if necessary modify, system information. In particular it can be used to examine system information for different tasks, the state of the memory allocation, etc.
See the **proc** man page for more information.
- In the event of a system crash, memory will be written to the configured disk location using **kdump**. Upon subsequent reboot, the data will be copied from the old memory and formatted into a **vmcore** file and stored in the **/var/crash/** subdirectory. The end result can then be analysed using the **crash** utility. An example command is shown below.

```
crash /usr/lib/debug/lib/modules/<kernel_version>/vmlinux vmcore
```



See Chapter 2 in the BAS5 for Xeon *Installation and Configuration Guide* for details on how to configure **kdump**.



Important:

It is essential to use non-stripped binary code within the kernel. Non-stripped binary code is included in the **debuginfo** RPM available from

<http://people.redhat.com/duffy/debuginfo/index-js.html>

This package installs the kernel binary in the folder

`/usr/lib/debug/lib/modules/<kernel_version>/`

2.5.4 Identifying problems in the different parts of a kernel

Various configuration parameters enable traces or additional checks to be used on different kernel operations, for example, locks, memory allocation and so on.

It is usually possible to focus the debug mode on the problematic part of the kernel which has been identified after recompilation. It is also possible to insert code, e.g. `printk`, to help examine the problematic part.

The different compilation tasks for a machine – stopping, starting, resetting, creating a dump, bootstrapping a compiled system and debugging may be carried out from a remote work station, connected to a development machine configured as a DHCP server.

2.6 Testing Maintenance Tools

2.6.1 Checking Nodes after Boot Phase (postbootchecker)

postbootchecker detects when a Compute Node is starting and runs check operations on this node after its boot phase. The objective is to verify that CPU and memory parameters are coherent with the values stored in the **ClusterDB**, and if necessary to update the ClusterDB with the real values.

2.6.1.1 Prerequisites

- **syslog-ng** must be installed and configured as follows:
 - Management Node: management of the logs coming from the cluster nodes.
 - Compute nodes: detection of the compute nodes as they start.
- The **postbootchecker** service must be installed before the RMS service, to avoid any disturbance for the jobs.

2.6.1.2 postbootchecker Checks for the Compute Nodes

The **postbootchecker** service (`/etc/init.d/postbootchecker`) detects every time a Compute Node starts. Whilst the node is starting up, **postbootchecker** runs three scripts to retrieve information about processors and memory. These scripts are the following:

Script name	Description
procTest.pl	Retrieves the number of CPUs available for the node.
memTest.pl	Retrieves the size of memory available for the node.
modelTest.pl	Retrieves model information for the CPUs available on the node.

Then **postbootchecker** returns this information to the Management Node using **syslog-ng**.

2.6.1.3 postbootchecker Checks for the Management Node

On the Management Node, the **postbootchecker** server gets information returned from the Compute Nodes and compares it with information stored in the ClusterDB:

- The number of CPUs available on the node is compared with the **nb_cpu_total** value in the ClusterDB.
- The size of memory available on the node is compared with the **memory_size** value in the ClusterDB.
- The CPUs model type on the node is compared with the **cpu_model** value in the ClusterDB.

If discrepancies are found, the ClusterDB is updated with the values retrieved. In addition, the Nagios status of the **postbootchecker** service is updated as follows:

- If the discrepancies concern the number of CPUs or the memory size the service is set to CRITICAL.
- If the discrepancies concern the model of the CPUs the service is set to WARNING.

If no discrepancies were found, the service is OK.

Chapter 3. Troubleshooting

Troubleshooting deals with the unexpected and is an important contribution towards maintaining a cluster in a stable and reliable condition. This chapter is aimed at helping you to develop a general, comprehensive methodology for identifying and solving problems on- and off-site.

The following topics are described:

- 3.1 *Troubleshooting Voltaire Networks*
- 3.2 *Troubleshooting InfiniBand Stacks*
- 3.3 *Node Deployment Troubleshooting*
- 3.4 *Storage Troubleshooting*
- 3.5 *Lustre Troubleshooting*
- 3.6 *Lustre File System High Availability Troubleshooting*
- 3.7 *SLURM Troubleshooting*
- 3.8 *FLEXlm License Manager Troubleshooting*

3.1 Troubleshooting Voltaire Networks

3.1.1 Voltaire's Fabric Manager

Voltaire's Fabric Manager enables **InfiniBand** fabric connectivity debugging using the built-in **Performance Manager (PM)**. **PM** has two major capabilities:

Port Counters Monitoring and Report

The **PM** generates a periodic port counters report file (in **CSV** format) that can be loaded to Excel and further analyzed by the user. It also monitors port counters errors and reports every port that passes its error threshold limit (as configured by the user).

Event Logging

This creates an event log file for both **IB** traps and **SubNet** internal events. The user may filter the events using a **GUI** and or a **CLI**. The filtering policy determines whether an event is logged and whether a trap is generated.

It is essential to identify any problem ports and node connectivity problems prior to running application as well as during standard operation.



Note:

See the *Voltaire Switch User Manual ISR 9024, ISR 9096, and ISR 9288/2012 Switches* for details on how to configure and use Port Counters and the Performance Manager. This manual also includes a description of all the **PortCounter** fields and counter values.

3.1.2 Fabric Diagnostics

Diagnostic is recommended in the following cases:

- During Fabric installation and during startup.
- Before running an application.
- Performance problems (by locating discarded packets and link integrity problems).
- MPI job run problem, to locate malfunctioning nodes and get the overall fabric structure.
- Additional problems related to fabric stability, blocking or other.

3.1.3 Debugging Tools

Tools available to perform diagnostic:

- Use the Topology Map to see current problems.
- The Error Log.
- The Bad Ports Log.
- The Current Alarms Table.
- The Fabric Statistics `portcounters.csv` file.

3.1.4 High-Level Diagnostic Tools

1. Enable the SM Fabric Inspect preferences for debugging Fabric Failure.
2. Use the VFM/VDM **Port Counters Information and Graph** window to check a specific port counter's health.
3. Use the **Event Log** to discover that there is a problem in the fabric. In the VFM, right click and select View Event to get information to help identify where problem is located. Alternatively, you can show the Event Log from the CLI.
4. Use the **Current Alarms** Table to see current problems. In the VFM, right click and select Alarm Data to get information to help identify where the problem is located.
5. Use the **Topology Map** to identify nodes with a current alarm.
6. Proactively look for increasing error counters using the statistics feature and running the Diagnostic scripts using the **CLI**.



Note:

See the *Voltaire Switch User Manual ISR 9024, ISR 9096, and ISR 9288/2012 Switches* for full details on using these tools.

3.1.5 CLI Diagnostic Tools

3.1.5.1 zero-counters script

To clear out all the errors across the fabric, use the **zero-counters** script to traverse the fabric and clear out all the port counters on both the switches and HCAs. This script is very easy to use and is helpful if you want to start off with a clean baseline of your fabric after many changes have occurred.

```
-----  
ISR9288(utilities) zero-counters  
Zero All Counters  
lid 1 ports 24  
*****  
lid 5 ports 24  
*****  
lid 4 ports 24  
*****  
lid 3 ports 24  
*****  
lid 2 ports 24  
*****  
lid 11 ports 24  
*****  
....  
-----
```



Note:

See the *Voltaire Switch User Manual ISR 9024, ISR 9096, and ISR 9288/2012 Switches* for full details on the CLI commands.

3.1.5.2 width-check script

Another valuable script is the **width-check** script which allows you to easily check the fabric for 1X connections links. While the fabric will work over a 1X connection, it will however create a bottleneck and hurt performance within the fabric. All links should report no 1X connections when the script is ran. Nothing else will be reported other than the LID and GUID if it's a full 4X link.

```
-----  
ISR9288(utilities) width-check  
  
Verify / every error found - will be printed  
  
lid 1 guid 0008f104004004d7 ports 24  
  
lid 5 guid 0008f104003f0723 ports 24  
lid 4 guid 0008f104003f0722 ports 24  
lid 3 guid 0008f104003f071f ports 24  
lid 2 guid 0008f104003f071e ports 24  
lid 11 guid 0008f104003f0747 ports 24  
lid 10 guid 0008f104003f0746 ports 24  
lid 7 guid 0008f104003f073b ports 24  
....  
-----
```

3.1.5.3 error-find script

The easiest way to look for errors on all ports in the fabric is to run the error-find script. It will report any non-zero port counters found throughout the fabric on both switches and HCAs.

```
-----
ISR9288(utilities) error-find

Show All Counter Errors / every error found - will be printed
lid 1 guid 0008f104004004d7 ports 24
lid 5 guid 0008f104003f0723 ports 24
port 22 xmitdiscards:.....4
port 10 linkdowned:.....1
port 13 lid 4 guid 0008f104003f0722 ports 24
port 14 errs.sym:.....83
-----
```

3.1.6 Event Notification Mechanism

Fabric related events can be generated by both the **PM** (Performance Monitor) and by the **SM** (Subnet Manager).

The **PM** periodically scans the error counters of all IB elements in the fabric and reports if a counter exceeds its threshold.

The **SM** monitors the fabric, detects configuration changes and dynamically configures the new elements and new routes in the fabric. The **SM** can detect fabric errors/warnings/informative events and report them.

Both, the **PM** and the **SM** generate events and report them to the event notification mechanism. In addition, events may be generated in the fabric and sent to the **SM** by fabric elements. The **SM** reports those events as well.

The event mechanism can do the following actions with each event:

- a. Log the event in the event log.
- b. Issue a trap to the GUI session.
- c. If the event corresponds to an alarm, it is also sent to the current alarm mechanism.

The GUI Color coding is defined according to traps and events severity, as described below.

GUI Color-Coding	Event Severity	Description	Examples
Red	Critical / Major	Critical means that the system or a system component fails to operate.	Invalid link Duplicate or conflicting ports or path
Yellow	Warning / Minor	Warning/minor reflects a problem in the fabric but does not prevent its operation. A warning is asserted when an event is exceeding a predefined threshold.	Broken link Illegal connections between two sLB ports
Green	Normal	Information/Notification provided to the user of normal operating state or a normal system event.	Complete subnet reconfiguration Create/Delete Multicast group Applied routing scheme Port State Change

3.2 Troubleshooting InfiniBand Stacks

A suite of **InfiniBand** diagnostic tools are provided with the Bull Advanced Server. There exists a hierarchical dependency for these tools, as shown in the diagram below. For example, **ibchecknet** is dependent on **ibnetdiscover**, **ibchecknode**, **ibcheckport** and **ibcheckerrs**.

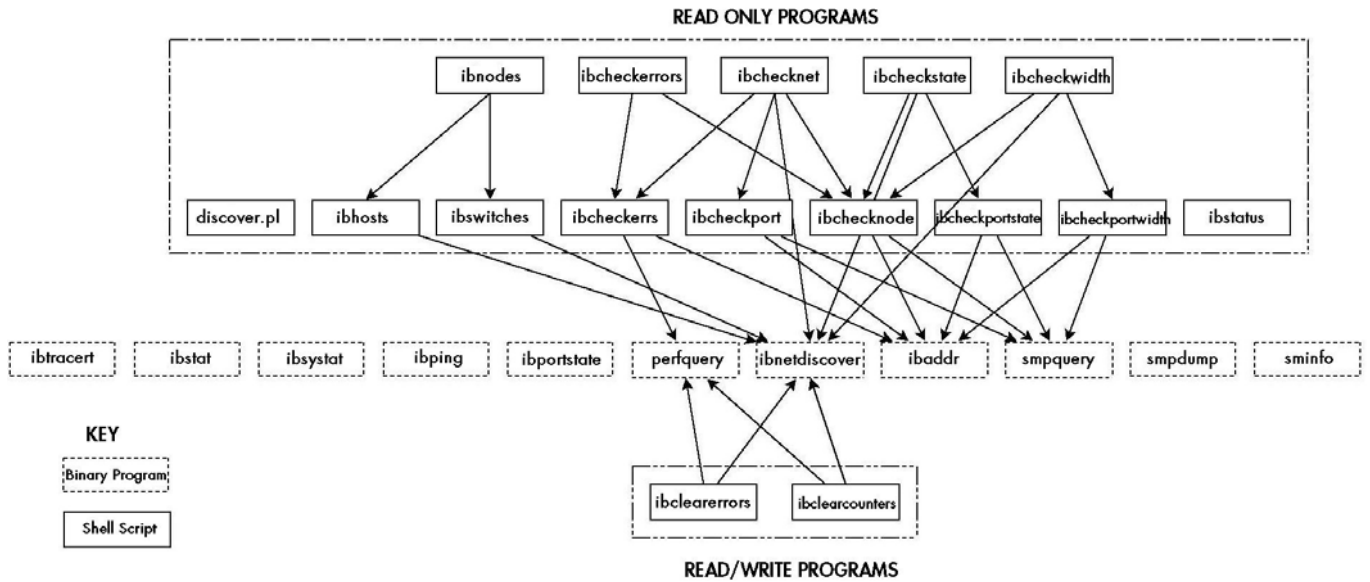


Figure 3-1. OpenIB Diagnostic Tools Software Stack

Use the following command to launch the diagnostic tools:

```
openib -diags
```

ibstatus, **ibtracert** and **ibdoctor** (a tool developed by Bull), are described in chapter 2 – *Day to Day Maintenance Operations*. Some of the more useful troubleshooting tools are described below.

3.2.1 smpquery

Subnet Manager Query (**smpquery**) includes a subset of standard SMP query options which may be used to bring up information – in a human readable format - for different parts of the network including nodes, ports and switches.

The basic syntax for the command is as follows:

```
smpquery [options] <op> <dest_addr> [op_params]
```

nodeinfo example:

An example of use of this command including the Local ID and the port number is below:

```
smpquery nodeinfo 45 1
```

The resulting information output will be similar to that displayed below:

```
-----  
BaseVers:.....1  
ClassVers:.....1  
NodeType:.....Channel Adapter  
NumPorts:.....2  
SystemGuid:.....0x0008f10403977ca7  
Guid:.....0x0008f10403977ca4  
PortGuid:.....0x0008f10403977ca6  
PartCap:.....64  
DevId:.....0x5a04  
Revision:.....0x000000a1  
LocalPort:.....2  
VendorId:.....0x0008f1  
-----
```

portinfo example:

An example of use of this command including the Local ID and the port number is below:

```
smpquery portinfo 45 1
```

The resulting information output will be similar to that displayed below:

```
-----  
Mkey:.....0x0000000000000000  
GidPrefix:.....0xfe80000000000000  
Lid:.....0x002d  
SMLid:.....0x0003  
CapMask:.....0x500a68  
IsTrapSupported  
IsAutomaticMigrationSupported  
IsSLMappingSupported  
IsLedInfoSupported  
IsSystemImageGUIDsupported  
IsVendorClassSupported  
IsCapabilityMaskNoticeSupported  
DiagCode:.....0x0000  
MkeyLeasePeriod:.....0  
LocalPort:.....2  
LinkWidthEnabled:.....1X or 4X  
LinkWidthSupported:.....1X or 4X  
LinkWidthActive:.....4X  
LinkSpeedSupported:.....2.5 Gbps  
LinkState:.....Active  
PhysLinkState:.....LinkUp  
LinkDownDefState:.....Polling  
ProtectBits:.....0  
LMC:.....0  
LinkSpeedActive:.....2.5 Gbps  
LinkSpeedEnabled:.....2.5 Gbps  
NeighborMTU:.....2048  
SMSL:.....0  
VLCap:.....VL0-7  
InitType:.....0x00  
VLHighLimit:.....0  
VLArbHighCap:.....8  
-----
```

```

VLArbLowCap:.....8
InitReply:.....0x00
MtuCap:.....2048
VLStallCount:.....7
HoqLife:.....13
OperVLs:.....VL0-7
PartEnforceInb:.....0
PartEnforceOutb:.....0
FilterRawInb:.....0
FilterRawOutb:.....0
MkeyViolations:.....0
PkeyViolations:.....0
QkeyViolations:.....0
GuidCap:.....32
ClientReregister:.....0
SubnetTimeout:.....18
RespTimeVal:.....1
LocalPhysErr:.....15
OverrunErr:.....0
MaxCreditHint:.....0
RoundTrip:.....0

```

switchinfo example:

An example of use of this command including the Local ID is below:

```
smpquery switchinfo 0x4
```

The resulting information output will be similar to that displayed below:

```

-----
LinearFdbCap:.....49152
RandomFdbCap:.....0
McastFdbCap:.....1024
LinearFdbTop:.....46
DefPort:.....0
DefMcastPrimPort:.....0
DefMcastNotPrimPort:.....0
LifeTime:.....15
StateChange:.....0
LidsPerPort:.....0
PartEnforceCap:.....32
InboundPartEnf:.....1
OutboundPartEnf:.....1
FilterRawInbound:.....1
FilterRawInbound:.....1
EnhancedPort0:.....0
-----

```

3.2.2 perfquery

perfquery uses Performance Management General Services Management Packets (**GMP**) to obtain the PortCounters (basic performance and error counters) from the Performance Management Attributes at the node specified.

The command syntax is shown below:

```
perfquery [options] [<lid|guid> [[port] [reset_mask]]]
```

Non standard flags:

- a** Show aggregated counters for all port of the destination lid.
- r** Reset counters after read.
- R** Only reset counters.

Examples

- To read local port's performance counters, enter:

```
perfquery
```

- To read performance counters from lid 32, port 1, enter:

```
perfquery 32 1
```

- To read node aggregated performance counters, enter:

```
perfquery -a 32
```

- To read performance counters and reset, enter:

```
perfquery -r 32 1
```

- To reset performance counters of port 1 only, enter:

```
perfquery -R 32 1
```

- To reset performance counters of all ports, enter:

```
perfquery -R -a 32
```

- To reset only non-error counters of port 2, enter:

```
perfquery -R 32 2 0xf000
```

Example output

The resulting information output will be similar to that displayed below

```
-----  
# Port counters: Lid 45 port 2  
PortSelect:.....2  
CounterSelect:.....0x0000  
SymbolErrors:.....0
```



```

LinkRecovers:.....0
LinkDowned:.....0
RcvErrors:.....0
RcvRemotePhysErrors:.....0
RcvSwRelayErrors:.....0
XmtDiscards:.....2
XmtConstraintErrors:.....0
RcvConstraintErrors:.....0
LinkIntegrityErrors:.....0
ExcBufOverrunErrors:.....0
VL15Dropped:.....0
XmtBytes:.....458424
RcvBytes:.....1908363
XmtPkts:.....6367
RcvPkts:.....41748

```

3.2.3 `ibnetdiscover` and `ibchecknet`

`ibnetdiscover` is used to scan the topology of the subnet and converts the output into a human readable form. Global IDs, node types, port numbers, port Local IDs and NodeDescriptions are displayed. The full topology is displayed including all nodes and links with the option of highlighting those which are currently connected. The output may be printed to a topology file.

Syntax:

```
ibnetdiscover [options] [<topology-filename>]
```

Non standard flags:

- l List of connected nodes
- H List of connected HCAs
- S List of connected switches

`ibchecknet` uses a topology file which has been created by `ibnetdiscover` to scan the network validating the connectivity and reporting errors detected by the port counters. The command runs as follows.

```
ibchecknet
```

A sample output is displayed below:

```

#warn: counter SymbolErrors = 65535      (threshold 10)
#warn: counter LinkRecovers = 26         (threshold 10)
#warn: counter LinkDowned = 16          (threshold 10)
#warn: counter RcvErrors = 21           (threshold 10)
#warn: counter RcvSwRelayErrors = 54810   (threshold 100)
#warn: counter XmtDiscards = 65535      (threshold 100)
Error check on lid 2 port all:  FAILED
#warn: counter RcvSwRelayErrors = 3995   (threshold 100)
Error check on lid 2 port 4:  FAILED
# Checked Switch: nodeguid 0x0008f104004118d8 with failure

# Checking Ca: nodeguid 0x0008f10403979970

# Checking Ca: nodeguid 0x0008f10403979860

```

```

# Checking Ca: nodeguid 0x0008f104039798ec
# Checking Ca: nodeguid 0x0008f1040397996c
# Checking Ca: nodeguid 0x0008f104039798e8
# Checking Ca: nodeguid 0x0008f10403979910
# Checking Ca: nodeguid 0x0008f104039798e4
# Checking Ca: nodeguid 0x0008f10403979920
# Checking Ca: nodeguid 0x0008f10403979948
# Checking Ca: nodeguid 0x0008f104039798f4
# Checking Ca: nodeguid 0x0008f104039798d0
# Checking Ca: nodeguid 0x0008f10403977ca4

## Summary: 13 nodes checked, 0 bad nodes found
##           24 ports checked, 0 bad ports found
##           1 ports have errors beyond threshold
-----

```

3.2.4 **ibcheckwidth** and **ibcheckportwidth**

ibcheckwidth checks all nodes, using the complete topology file which was created by **ibnetdiscover**, to validate the bandwidth for links which are active and will also identify ports with 1X bandwidth.

```
ibcheckwidth
```

Output Example

```

## Summary: 40 nodes checked, 0 bad nodes found

##           140 ports checked, 0 ports with 1x width in error found
-----

```

ibcheckportwidth checks connectivity and the link width for a given port lid and will indicate the actual bandwidth being used by the port. This should be checked against the maximum which is possible. For example, if the port supports 4 x bandwidth then this should be used. Similarly, if the adapter supports DDR then this should be used.

Syntax:

```
ibcheckportwidth [-h] [-v] [-G] <lid | guid> <port>
```

Example:

```
ibcheckportwidth -v 0x2 1
```

Output:

```
Port check lid 0x2 port 1: OK
-----
```

3.2.5 More Information

Please refer to the man pages for more information on the all tools described in this section and also on the other **OpenIB** tools which are available.

3.3 Node Deployment Troubleshooting

ksis is the deployment tool used to deploy node images on Bull HPC systems. This section describes how deployment problems are logged by **ksis** for different parts of the deployment procedure.

3.3.1 **ksis** deployment accounting

Following each deployment **ksis** take stock of the nodes, and identifies those that have had the image successfully deployed onto them, and those that have not.

This information is listed in the files below, and remains available until the next image deployment:

- List of nodes successfully deployed to - `/tmp/ksisServer/ksis_nodes_list`
- List of nodes not deployed to - `/tmp/ksisServer/ksis_exclude_nodes_list`

When the image has failed to be deployed to a particular node, **Ksis** adds a line in the `ksis_exclude_nodes_list` file to indicate:

- a. The name of the node (between square brackets)
- b. The consequences of the problem for the node.
Three states are possible:
 - **not touched** The node was excluded by the deployment with no impact (for the node).
 - **restored** The configuration of the node was modified, but its initial configuration was able to be restored.
 - **corrupt** The node was corrupted by the operation.
- c. The circumstance which led to the deployment problem.

Example:

```
[node2] not touched: node is configured-in
```

Most of the time, the information in the excluded node list allows the source of the problem to be identified, without the need for further analysis.

3.3.2 Possible Deployment Problems

There are 2 areas where deployment problems may occur.

3.3.2.1 Pre-check problems

Before the image is deployed, node states are verified in the **ClusterDB** Database, and through the use of **nsm** commands. If there are any problems, the nodes in question will be excluded for the deployment.

The error will be displayed once the deployment has finished, and will also be logged in the `/tmp/ksisServer/ksis_exclude_nodes_list` file.

3.3.2.2 Image transfer problems

Problems may occur during the phase when the image is being transferred onto the target nodes. These problems are logged and centralised by **Ksis** on the Management Node.

The errors will be displayed once the deployment has finished, and will also be logged in the `/tmp/ksisServer/ksis_exclude_nodes_list` file.

ksis image server logs

ksis server logs are saved on the Management Node in `/var/lib/systemimager/overrides/ka-d-server.log`

and

Ksis server traces are saved on the Management Node in `/var/lib/systemimager/overrides/server_log`



Note

Traces are only possible for the **ksis** server, and for client nodes, if the **ksis deploy** command is executed using the `-g` option.

ksis image client logs

ksis client logs on the Management Node in `/var/lib/systemimager/overrides/imaging_complete_<nodeIP>`
or
`/var/lib/systemimager/overrides/patching_complete_<nodeIP>`
or
`/var/lib/systemimager/overrides/unpatching_complete_<nodeIP>`

and **ksis** client traces on the Management Node in `/var/lib/systemimager/overrides/imaging_complete_error_<nodeIP>`

These traces will only be logged if the deployment error occurs on the client side.

Patch deployment client traces on the Management Node in `/var/lib/systemimager/overrides/patching_complete_error_<nodeIP>`
or
`/var/lib/systemimager/overrides/unpatching_complete_error_<nodeIP>`

The client log files will be used during the post-check phase. **Ksis** client and image server errors are compared in order to identify the source of any problems which may occur.

The trace files are kept for support operations.

3.4 Storage Troubleshooting

This section provides some tips to help the administrator troubleshoot a storage configuration.

3.4.1 Management Tools Troubleshooting

3.4.1.1 Verbose Mode (-v Option)

Some of the storage commands have a `-v` (verbose) option, which provides more output information during the processing of the command.



See: *Bull HPC BAS5 for Xeon Administrator's Guide* for an inventory of storage commands supporting the `-v` option.

3.4.1.2 Log/Trace System

Principle

If the verbose mode is not enough, a system of traces can also be configured to obtain more information on some commands. To activate these traces you can set the trace level in the appropriate `/etc/storageadmin/*.conf` file.

There are two lines in these files to set the trace. These lines look as follows, where `<command_name>` is the name of the command to debug:

```
#<command_name>_TRACE_STDOUT_LEVEL =  
#<command_name>_TRACE_LOG_FILE_LEVEL =
```

The first line is used to activate traces on stdout, the second one is used to generate traces in a `/tmp/storregister.PID.traces` log file. By default the two lines are in comment.



Note: It is recommended to use this trace tool only for temporary debugging because there is no automatic cleaning of the `/tmp/<command_name>.PID.traces` log files.

Four levels of traces are available:

- 4 => TRACE_LEVEL_DEBUG
- 3 => TRACE_LEVEL_INFO
- 2 => TRACE_LEVEL_WARNING
- 1 => TRACE_LEVEL_ERROR

Level 4 is the most verbose level, level 1 traces only error messages.



Note: It is not possible to add new commands. All the commands accepting this system of traces are listed in the corresponding `*.conf` file.



See: *Bull HPC BAS5 for Xeon Administrator's Guide* to identify the right configuration file.

Example:

The following example explains how to obtain log file and/or stdout traces on **storregister** command.

1. Find the right **/etc/storageadmin/*.conf** file to modify. In the case of the **storregister** command, it is **storframework.conf** because of the presence of these two lines:

```
# storregister_TRACE_STDOUT_LEVEL =  
# storregister_TRACE_LOG_FILE_LEVEL =
```

2. Edit the **storframework.conf** file:

- Uncomment one of the two previous lines.

- Choose a level of trace between 1 (lowest) and 4 (highest) level.

For example, to add traces of debug level (4 = highest level) on stdout only, the **storframework.conf** file must contain the following lines:

```
# STDOUT trace level configuration :  
...  
storregister_TRACE_STDOUT_LEVEL = 4  
...  
# log file trace level configuration :  
# storregister_TRACE_LOG_FILE_LEVEL =
```

3. Save the **storframework.conf** file.
4. Relaunch **storregister**. New traces will appear on the stdout.

3.4.1.3 Available Troubleshooting Options for Storage Commands

The following table sums up the available troubleshooting options for the storage commands.

Command	User Command	-v option	Log/Traces	Name of the corresponding .conf File
fcswregister	Yes			
iorefmgmt	Yes			
ioshowall	Yes			
lsiocfg	Yes	Yes		
lsiodev	Yes			
nec_admin	Yes		Yes	nec_admin.conf
nec_stat	Yes			
stordepha	Yes			
storcheck	Yes		Yes	storframework.conf
stordepmap	Yes	Yes		
stordiskname	Yes			
storiocellctl	Yes		Yes	storframework.conf
storioha	Yes			

Command	User Command	-v option	Log/Traces	Name of the corresponding .conf File
storiopathctl	Yes		Yes	storframework.conf
stormap	Yes	Yes		
stormodelctl	Yes		Yes	storframework.conf
storregister	Yes		Yes	storframework.conf
storstat	Yes		Yes	storframework.conf
stortrapd	No		Yes	storframework.conf
stortraps	No		Yes	storframework.conf

Table 3-1. Available troubleshooting options for storage commands

3.4.1.4 nec_admin Command for Bull FDA Storage Systems

The **nec_admin** command is used to manage Bull FDA Storage Systems. This command interacts with the FDA CLI. A retry mechanism has been implemented to manage the fact that the CLI may reject commands when overloaded. If, despite default setting, the **nec_admin** command occasionally fails, you may change the timeout and retry values defined in the `/etc/storageadmin/nec_admin.conf` file.

```
# Number of retries in case of iSMserver Busy (Not Mandatory)
retry = 3

# If "retry" is set: time in second between two retries (Not Mandatory)
rtime = 5

# Timeout value : when timeout is reached, the command is considered as
failed
# If number of retries does not exceed the "retry" value, the
# command is launched again, otherwise it is failed.
cmdtimeout = 300
```



See: *Bull HPC BAS5 for Xeon Administrator's Guide* for more details about the **nec_admin** command.

3.5 Lustre Troubleshooting

The following section helps you troubleshoot some of the problems affecting your Lustre file system. Because typographic errors in your configuration script or your shell script can cause many kinds of errors, check these files first when something goes wrong.

First be sure your File-system is mounted and you have mandatory user rights.

3.5.1 Hung Nodes

There is no way to clear a hung node except by rebooting. If possible, un-mount the clients, shut down the MDS and OSTs, and shut down the system.

3.5.2 Suspected File System Bug

If you have rebooted the system repeatedly without following complete shutdown procedures, and Lustre appears to be entering recovery mode when you do not expect it, take the following actions to cleanly shut down your system.

1. Stop the login nodes and all other Lustre client nodes. Include the **-F** option with the **lustre_util** command to un-mount the file system.

```
#lustre_util umount -F -f <file_system> -n <node_name>
```

2. Shut down the rest of the system.
3. Run the **e2fsck** command.

3.5.3 Cannot re-install a Lustre File System if the status is CRITICAL

If the status of a file system is CRITICAL (according to the **lustre_util status** command), and if the file system needs to be re-installed (for instance if some nodes of the cluster have been deployed and reconfigured), it is possible that the file system description needs to be removed from the cluster management database, as shown below:

1. Run the following command to install the **fs1** file system:

```
lustre_util install -f /etc/lustre/models/fs1.lmf
```

The command may issue an output similar to:
file system already installed, do "remove" first

2. Run the following command to remove the **fs1** file system:

```
lustre_util remove -f fs1
```

The command may fail with a message similar to:
file system not loaded, try to give the full path
If it is not possible to re-install neither remove the file system with force option (-F).

The **lustre_fs_dba** command can then be used to remove the file system information from the cluster management database.

For example, to remove the `fs1` file system description from the cluster management database, enter the following command:

```
lustre_fs_dba del -f fs1
```

After this command the file system can be re-installed using the **lustre_util install** command.

3.6 Lustre File System High Availability Troubleshooting

Before using a Lustre file system configured with the High Availability (HA) feature, or in the event of abnormal operation of HA services, it is important to perform a check-up of the Lustre HA file system. This section describes the tools that allow you to make the required checks.

3.6.1 On the Management Node

The following tools must be run from the management node.

`lustre_check`

This command updates the `lustre_io_nodes` table in the ClusterDB. The `lustre_io_nodes` table provides information about the availability and the state of the I/O nodes and metadata nodes.

`lustre_migrate nodestat`

This command provides information about the node migrations carried out. It indicates which nodes are supposed to support the OST/MDT services.

In the following example, the MDS are `nova5` and `nova9`, the I/O nodes are `nova6` et `nova10`. `nova5` and `nova6` have been de-activated, so their services have migrated to their pair-nodes (`nova9` and `nova10`).

```
lustre_migrate nodestat
```

```
HA paired nodes status
-----
node name  node status  HA node name  HA node status
nova5      MIGRATED    nova9         OK
nova6      MIGRATED    nova10        OK
```

 **Note:** This table is updated by the `lustre_check` command.

`lustre_migrate hastat [-n <node_name>]`

This command indicates how the Lustre failover services are dispatched, after CS4 software has been activated.

Each node has a view on the paired failover services (the failover service dedicated to the node and the failover service dedicated to its pair node). If the pair-node has switched roles, the `owner` column of the command output will show that this node supports the two `lustre_HA` services.

In the following example, `nova6` and `nova10` are paired I/O nodes. The `lustre_nova6` service is started on `nova10` (owner node). This status is consistent on both `nova6` and `nova10` nodes.

```
lustre_migrate hastat -n nova[6,10]
```

```
-----
nova10
-----
Member Status: Quorate, Group Member
Member Name          State      ID
-----
nova6                Online    0x0000000000000001
nova10              Online    0x0000000000000002
Service Name        Owner (Last)      State
-----
lustre_nova10      nova10            started
lustre_nova6       nova10            started
-----
nova6
-----
Member Status: Quorate, Group Member
Member Name          State      ID
-----
nova10              Online    0x0000000000000002
nova6              Online    0x0000000000000001
Service Name        Owner (Last)      State
-----
lustre_nova10      nova10            started
lustre_nova6       nova10            started
-----
```

To return to the initial configuration, you should stop `lustre_nova6` which is running on `nova10` and start it on `nova6`, using the `lustre_migrate relocate` command.

lustre_util status

This command displays the current state of the Lustre file systems.



Important:

Sometimes this command can simply indicate that the recovery phase has not finished; in this situation the status will be set to "WARNING" and the remaining time will be displayed.



Important:

When an I/O node have been completely re-installed following a system crash, the **Lustre** configuration parameters will have been lost for the node. They need to be redeployed from the Management Node by the system administrator. This is done by coping all the configuration files from the Management Node to the I/O node in question by using the `scp` command as shown below:

```
scp/etc/lustre/conf/<fs_name>.xml<io_node_name>:/etc/lustre/conf/<fs_name>.xml
```

<fs_name> is the name for each file system that was included on the I/O node before the crash.

lustre_util info

This command provides detailed information about the current distribution of the OSTs/MDTs. The services and their status are displayed, along with information about the primary, secondary and active nodes.

[/tmp/log/lustre/lustre_HA-ddmm.log](#)

This file provides a trace of the commands issued by the nodes to update the LDAP and ClusterDB databases. This information should be compared with the actions performed by CS5.



Note:

In [lustre_HA-ddmm.log](#), *dd* specifies the day and *mm* the month of the creation of the file.

[/var/log/lustre/HA-DBDaemon=yy-mm-dd.log](#)

This file provides a trace of any ClusterDB updates that result from the replication of LDAP. This could be useful if **Lustre** debug is activated at the same time.

3.6.2 On the Nodes of an I/O Pair

The following tools must be run from the I/O nodes.

[ioshowall](#)

This command allows the configuration to be checked.

Look at the [/etc/cluster/cluster.conf](#) file for any problems if the following error is displayed:

```
-- cannot connect to < PAP address> or HWMANAGER
```

Check if the node is an inactive pair-node if the following error appears, otherwise start the node again:

```
-- service lustre_ha inactif
```

[clustat](#)

Displays a global status for Cluster Suite 4, from the HA cluster point of view.



Important: If there is a problem, the two pair nodes may not have the same view of the HA cluster state.

[storioha -c status](#)

This command checks that all the Cluster Suite 4 processes are running properly ("running state").



Notes:

- This command is equivalent to the following one on the Management Node:
`stordepha -c <status> -i <node>`
- This command is included in the global checking performed by the [ioshowall](#) command.

stormap -l

This command checks the state of the virtual links.



Note: This command is included in the global checking performed by the `ioshowall` command.

lctl dl

This command checks the current status of the OST/MDT services on the node.

For example:

```
1 UP lov fs1_lov-e0000047fcfff680 b02a458d-544e-974f-8c92-23313049885e 4
2 UP osc OSC_nova9_ost_nova6.ddn0.11_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
3 UP osc OSC_nova9_ost_nova10.ddn0.5_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
4 UP osc OSC_nova9_ost_nova6.ddn0.3_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
5 UP osc OSC_nova9_ost_nova10.ddn0.21_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
6 UP osc OSC_nova9_ost_nova6.ddn0.19_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
7 UP osc OSC_nova9_ost_nova10.ddn0.7_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
8 UP osc OSC_nova9_ost_nova6.ddn0.1_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
9 UP osc OSC_nova9_ost_nova10.ddn0.23_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
10 UP osc OSC_nova9_ost_nova6.ddn0.17_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
11 UP osc OSC_nova9_ost_nova10.ddn0.13_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
12 UP osc OSC_nova9_ost_nova6.ddn0.9_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
13 UP osc OSC_nova9_ost_nova10.ddn0.15_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
14 UP mdc MDC_nova9_mdt_nova5.ddn0.25_MNT_clientelan-e0000047fcfff680
b02a458d-544e-974f-8c92-23313049885e 4
```

The last line indicates the state of the MDC, which is the client connecting to the MDT (on the MDS).

The other lines indicate the state of the OSC, which are the clients connecting to each OST (on the `nova6` and `nova10` OSS).

[/var/log/lustre/HA_yy-mm-dd.log](#)

This file provides a trace of the calls made by CS5 to the Lustre failover scripts.



Note:

In the `HA_yy-mm-dd.log` file, `yy` specifies the year, `mm` the month and `dd` specifies the day of the creation of the file.

[/var/log/syslog](#)

This file provides a trace of the events and activity of CS5 and Lustre.

Recovering consistent state of HA system

In some very specific cases, it may be necessary to reset the HA system to a state which ensures consistency across the pair-nodes, **without stopping** the Lustre system.

1. Disconnect the `fs1` Lustre File System from the HA system:

```
lustre_ldap unactive -f fs1
```

Now, no operation on the HA system is passed on to the Lustre File System.

2. Run:

```
storioha -c stop  
clustat
```

3. Perform one of the following actions:

- To move a node from primary state to pair-node state, run:

```
lustre_migrate export -n <node_name>
```

- Or, to reset the switched node back to its primary state, run:

```
lustre_migrate relocate -n <node_name>
```

4. Re-connect the Lustre File System to the Lustre HA system:

```
lustre_ldap active -f fs1
```

5. Run:

```
storioha -c start
```

3.7 SLURM Troubleshooting

3.7.1 SLURM does not start

Check that all the RPMs have been installed on the Management Node by running the command below.

```
rpm -qa | grep slurm
```

The following RPMs should be listed:

```
slurm-x.x.xx-x.Bull  
slurm-auth-none- x.x.xx-x.Bull  
pam_slurm-x.x- x.x.xx-x.Bull  
slurm-auth-munge- x.x.xx-x.Bull
```



Note:

The version numbers depend on the release and are indicated by the letter x above.

3.7.2 SLURM is not responding

1. Run the command **scontrol ping** to determine if the primary and backup controllers are responding.
2. If they respond, then there may be a Network or Configuration problem – see section 3.7.5 *Networking and Configuration Problems*.
3. If there is no response, log on to the machines to rule out any network problems.
4. Check to see if the **slurmctld** daemon is active by running the following command:

```
ps -ef | grep slurmctld
```

- a. If **slurmctld** is not active, restart it as the root user using the following command.

```
service slurm start
```

- b. Check the **SlurmctldLogFile** file in the **slurm.conf** file for an indication of why it failed.
- c. If **slurmctld** is running but not responding (a very rare situation), then kill and restart it as the root user using the following commands:

```
service slurm stop  
service slurm start
```


- d. If it hangs again, increase the verbosity of debug messages by increasing **SlurmctldDebug** in the **slurm.conf** file, and restart. Again, check the log file for an indication of why it failed.

5. If SLURM continues to fail without an indication of the failure mode, stop the service, add the controller option "-c" to the `/etc/slurm/slurm.sh` script, as shown below, and restart.

```
service slurm stop
```

```
SLURM_OPTIONS_CONTROLLER="-c"
```

```
service slurm start
```

 **Note:** All running jobs and other state information will be lost when using this option.

3.7.3 Jobs are not getting scheduled

1. This is dependent upon the scheduler used by **SLURM**. Run the following command to identify the scheduler.

```
scontrol show config | grep SchedulerType
```

See the *Bull HPC Administrator's Guide* for a description of the different scheduler types.

2. For any scheduler, the priorities of jobs can be checked using the following command:

```
scontrol show job
```

3.7.4 Nodes are getting set to a DOWN state

1. Check to determine why the node is down using the following command:

```
scontrol show node <name>
```

This will show the reason why the node was set as down and the time when this happened. If there is insufficient disk space, memory space, etc. compared to the parameters specified in the `slurm.conf` file, then either fix the node or change `slurm.conf`.

For example, if the temporary disk space specification is `TmpDisk=4096`, but the available temporary disk space falls below 4 GB on the system, **SLURM** marks it as down.

2. If the reason is '*Not responding*', then check the communication between the Management Node and the DOWN node by using the following command:

```
ping <address>
```

Check that the `<address>` specified matches the `NodeAddr` values in the `slurm.conf` file. If ping fails, then fix the network or the address in the `slurm.conf` file.

3. Login to the node that **SLURM** considers to be in a DOWN state and check to see if the **slurmd** daemon is running using the following command:

```
ps -ef | grep slurmd
```

4. If **slurmd** is not running, restart it as the root user using the following command:

```
service slurm start
```

5. Check **SlurmdLogFile** file in the **slurm.conf** file for an indication of why it failed.
 - a. If **slurmd** is running but not responding (a very rare situation), then kill and restart it as the root user using the following commands:


```
service slurm stop  
service slurm start
```

6. If the node is still not responding, there may be a Network or Configuration problem – see section 3.7.5 *Networking and Configuration Problems*.
7. If the node is still not responding, increase the verbosity of debug messages by increasing **SlurmdDebug** in the **slurm.conf** file, and restart. Again, check the log file for an indication of why it failed.
8. If the node is still not responding without an indication as to the failure mode, stop the service, add the daemon option "-c" to the **/etc/slurm/slurm.sh** script, as shown below, and restart.

```
service slurm stop
```

```
SLURM_OPTIONS_DAEMONS="-c"
```

```
service slurm start
```

 **Note:** All running jobs and other state information will be lost when using this option.

3.7.5 Networking and Configuration Problems

1. Use the following command to examine the status of the nodes and partitions:

```
sinfo --all
```

2. Use the following commands to confirm that the control daemons are up and running on all nodes:

```
scontrol ping  
scontrol show node
```

3. Check the controller and/or **slurmd** log files (**SlurmctldLog** and **SlurmdLog** in the **slurm.conf** file) for an indication of why a particular node is failing.

4. Check for consistent **slurm.conf** and credential files on the node(s) experiencing problems.
5. If the problem is a user-specific problem, check that the user is configured on the Management Node as well as on the Compute Nodes. The user does not need to be able to login, but his user ID must exist. User authentication must be available on every node. If not, non-root users will be unable to run jobs.
6. Verify that the security mechanism is in place, see chapter 6 in the *Bull HPC BAS5 for Xeon Administrator's Guide* for more information on SLURM and security.
7. Check that a consistent version of SLURM exists on all of the nodes by running one of the following commands:

```
sinfo -V
```

or

```
rpm -qa | grep slurm
```

If the first two digits of the version number match, it should work fine. However, version 1.1 commands will not work with version 1.2 daemons or vice-versa.

Errors can result unless all these conditions are true.

8. Each node must be synchronized to the correct time. Communication errors occur if the node clocks differ.

Execute the following command to confirm that all nodes display the same time:

```
pdsh -a date
```

To check a group of nodes use the following command:

```
pdsh w <node list> date
```

A matter of a few seconds is inconsequential, but SLURM is unable to recognize the credentials of nodes that are more than 5 minutes out of synchronization. See Chapter 2 in the *Bull HPC BAS5 for Xeon Installation and Configuration Guide* for information on setting node times using the **NTP** protocol.

3.7.6 More Information

For more information on SLURM Troubleshooting see the *Bull HPC BAS5 for Xeon Administrator's Guide*, *Bull HPC BAS5 for Xeon User's Guide* and <http://www.llnl.gov/linux/slurm/slurm.html>

3.8 FLEXlm License Manager Troubleshooting

3.8.1 Entering License File Data

You can edit the hostname on the server line (first argument), the port address (third argument), the path to the vendor-daemon on the VENDOR line (if present), or any right half of a string (b) of the form a=b where (a) is all lower case. Any other changes will invalidate the license.

Be cautious when transferring data received by Mailers. Many Mailers add characters at the end-of-line that may confuse the reader about the real license data.

3.8.2 Using the `lmdiag` utility

The `lmdiag` command analyzes a license file with respect to the SERVER, the FEATURES, license counts and dates. It may help you to understand problems that may occur. `lmdiag` attempts to checkout all FEATURES and explains failures. You may run extended diagnostics attempting to connect to the license manager on each port on the host.

3.8.3 Using `INTEL_LMD_DEBUG` Environment Variable

Setting this environment variable will cause the application to produce product diagnostic information at every checkout.

Daemon Startup Problems.

Cannot find license file. Most products have a default location in their directory hierarchy (or use `/opt/intel/licenses/server.lic`). The environment variable `INTEL_LICENSE_FILE` names this directory. Startup may fail if these variables are set wrong, or the default location for the license is missing.

No such Feature exists

The most common reason for this is that the wrong license file, or an outdated copy of the file, is being used.

Retrying Socket Bind

This means the TCP port number is already in use. Almost always, this means an `lmgrd.intel` is already running, and you have tried to start it twice. Sometimes it means that another program is using this TCP port number. The number is listed on the SERVER line in the license file as the last item. You can change the number and restart `lmgrd.intel`, but only do this if you do not already have an `lmgrd.intel` running for this license file.

INTEL: cannot initialise

```
(INTEL) FLEXlm version 7.2
(lmgrd) Please correct problem and restart daemons
```

You may be starting the **lmgrd.intel** from the wrong directory, or with relative paths. Use the following lines in the start up and add a full root path to 'INTEL' to the end of the VENDOR line in the license file:

```
cd <installation-directory>
`pwd`/lmgrd.intel -c `pwd`/server.lic -l `pwd`/lmgrd.intel.log
```

License manager: cannot initialize: Cannot find license file

You have started **lmgrd.intel** on a non-existent file. The recommended way to specify the file for **lmgrd.intel** to use -c <license>:

```
cd <installation-directory>
`pwd`/lmgrd.intel -c `pwd`/server.lic -l `pwd`/lmgrd.intel.log
```

Invalid license key (inconsistent encryption code for 'FEATURE')

This happens for 3 different reasons:

1. The license file has been typed in incorrectly.
(Cutting and pasting from email is a safe way to avoid this). Or the data have been altered by the end user. See "Entering License File Data" above.
2. The license is generated incorrectly. Your vendor will have to generate a new license if this is the case.
3. The license vendor has changed encryption seeds (rare).

MULTIPLE vendor-daemon-name servers running

There are 2 **lmgrd** and vendor-daemons running for this license file. Only one process per vendor-daemon/per node is allowed to run. Sometimes this can happen because the **lmgrd** was killed with a -9 signal (which should not be done!). The **lmgrd** was then not able to bring the vendor-daemon process down, so it's still running, although not able to serve licenses.

If **lmgrd** is killed with a -9, the vendor-daemons also then must be killed with a -9 signal. In general, **lmdown** should be used.

Vendor daemon cannot talk to lmgrd

This means a pre-version-3.0 **lmgrd** version is being used with a 3.0+ vendor daemon. Simply use the latest version of **lmgrd** (MUST be a version equal to or greater than the vendor daemon version). This can also happen if TCP networking does not function on the node where you are trying to run **lmgrd** (rare).

No licenses to serve

The license file has only 'uncounted' licenses, and these do not require a server. Uncounted licenses have a '0' or 'uncounted' in the 'number-of-licenses' field on the FEATURE line.

Other Starting **lmgrd.intel** from a remote directory may lead to unknown results. If **lmgrd.intel** is started from a remote directory the license file line:

```
VENDOR INTEL
```

Should be modified to include the root directory where the 'INTEL' vendor daemon resides:

```
VENDOR INTEL <root-directory-path>
```

The **lmgrd.intel** daemon MUST be started with the -c argument:

```
cd <installation-directory>
`pwd`/lmgrd.intel -c `pwd`/server.lic -l `pwd`/lmgrd.intel.log
```

Application Execution Problems

```
Cannot connect to license server
```

Usually this means the server is not running. It can also mean the server is using a different copy of the license file, which has a different port number than the license file you are currently using indicates. You can use the **lmdiag** utility to more fully analyze this error.

License Server does not support this Feature

This means the server is using a different copy of the license file than the application. They should be synchronized. This error will also report "UNSUPPORTED" in the debug log file.

Invalid Host

You may be attempting to run the application on a host not listed in the "HOSTID" field of your license. Use **lmhostid** to find the hostid number for the current host.

```
Cannot find license file. No such file or directory
Expected license file location: <path>
```

The application was not able to find a license file. It gives you the location(s) where it was looking for a license file.

Check that the named file exists. To use a file at a different location, use the environment variable INTEL_LICENSE_FILE.

No such Feature exists

The license manager cannot find a 'FEATURE' line in the license file.

Feature has expired

Your license has expired. The system time may be set incorrectly. Run the 'date' command to make sure the date is not later than the Expiration Date listed in the license file.

```
<FEATURE name>: Invalid (inconsistent) license key
```

The license-key and data for the feature do not match. This usually happens when a license file has been altered. See "Entering License File Data" above.

System Bootup Problems

For reasons unknown some bootup files (/etc/rc, /sbin/rc2.d, etc) refuse to run **lmgrd** with the simple commands indicated above. Here are two workarounds:

1. Use 'nohup su username -c 'umask 022;lmgrd -c ...' (It is not recommended to run **lmgrd** as root; the "su username" is used to run **lmgrd** as a non-privileged user.)
2. Add 'sleep 2' after the **lmgrd** command.

Chapter 4. Accessing, Updating and Reconfiguring the BMC Firmware on NovaScale R4xx machines

This chapter describes how to update the BMC firmware on NovaScale R421, R422, R422 E1, R423, R440 and R460 machines.

4.1 The Baseboard Management Controller (BMC)

The Baseboard Management Controller (BMC) is used to monitor the hardware sensors for temperature, cooling fan speeds, power mode, etc., and to report any hardware errors by sending alerts. It is also used for basic system management operations such as starting, stopping and resetting a cluster. It also provides a remote console on the cluster nodes via Serial over LAN access (SOL).

The **BMC** is the intelligence in the Intelligent Platform Management Interface (IPMI) architecture. The **BMC** manages the interface between system management software and platform hardware.

There are several ways to access the **BMC** of a machine.

4.1.1 Local access to the BMC

The BMC of the local machine can be accessed using the **ipmitool** command.



See Chapter 2 in this manual or the man page for more information

The **IPMI** service must be started to access the local **BMC** via the IPMI driver:

```
service ipmi start
```

Examples

1. To obtain the BMC LAN configuration on a local NovaScale R42x machine (channel #1), run the command below:

```
ipmitool lan print 1
```

2. To obtain the BMC LAN configuration on a local NovaScale R440 or R460 machine (channel #2), run the command below:

```
ipmitool lan print 2
```

4.1.2 Remote access to the BMC

4.1.2.1 Command Line Remote access

The **BMC** of a remote node can be accessed using the **ipmitool** command (*man ipmitool*), or the higher level, cluster-oriented **conman** or **NS commands** – See Chapter 2 in this manual.

Examples using the **ipmitool** command:

1. To obtain the **BMC LAN** configuration for a **NovaScale R42x** machine (channel #1):

```
ipmitool -H <BMC IP addr> -U ADMIN -P ADMIN lan print 1
```

2. To shutdown a remote machine:

```
ipmitool -H <BMC IP addr> -U ADMIN -P ADMIN power soft
```

3. To connect to a remote console via SOL for **NovaScale R421, R422, R422 E1, R423, R440** and **R460** machines:

```
ipmitool -I lanplus -H <BMC IP addr> -U ADMIN -P ADMIN sol activate
```

Enter ~. to terminate the connection.

4. To connect to a remote console via SOL for a **NovaScale R421 E1** machine:

```
ipmitool -I lanplus -H <BMC IP addr> -U ADMIN -P ADMIN -o intelplus  
sol activate
```

4.1.2.2 Tips for using ipmitools and SOL

- If the payload is already active for another session it can be deactivated by running the **ipmitool ... sol deactivate** command.
- The escape character can be changed to **&** to prevent conflicts with **ssh**.
- Use the **ESC** and the number **2** keys instead of using the **F2** key to access the BIOS on **NovaScale R440** and **R460** machines.
- Use the **ESC** and the **-** (minus) keys instead of using the **DEL** key to access the BIOS on **NovaScale R421** and **R422** machines.

4.1.2.3 Web remote access

The BMC can be accessed using a web interface for **Novascale R421, R422, R422 E1** and **R423** machines.



See the **Bull NovaScale R42x AOC- SIMSO/SIMSO+ Installation and User's Guide** for more information

The Web interface provides access to the **SOL** console or the **KVM** console (**SIMSO+**) and also the means to access virtual devices for maintenance purposes.

To access the **BMC** of a remote machine through the Web interface:

1. The following RPMs found in the BONUS directory on the Bull XHPC DVD must be installed on the Management Node:

XHPC/BONUS/jre-<version>-linux-i586.rpm

XHPC/BONUS/firefox-<version>-Bull.0.i386.rpm

These are installed by running the commands below:

```
cd /release/XBAS5V1.1/XHPC/BONUS
rpm -i jre-<version>-linux-i586.rpm firefox-<version>-Bull.0.i386.rpm
```

2. The java plug-in should be configured using Firefox:

```
ln -s /usr/java/jre1.<version>/plugin/i386/ns7/libjavaplugin_oji.so
/usr/local/firefox/plugin
```

3. The remote BMC is accessed using the command below:

```
/usr/local/firefox/firefox
```

4. In the navigation bar, enter the URL:

```
http://<BMC IP addr>
```

4.2 Updating the BMC Firmware on NovaScale R421, R422, R422 E1 and R423 machines

These platforms use the **BMC SIMSO** or **SIMSO+** add-on boards for platform management. Both boards provide IPMI 2.0 functions. The **SIMSO+** board provides additional **KVM** over **LAN** functionality.

The **BMC** firmware, and the tool needed to carry out the upgrade, are included on the following RPM: `update-bmc-fw-<BMC firmware version>.Bull.x86_64.rpm`.

The BMC firmware of the **SIMSO** board can be updated under **Linux** using the `updatefw.x86_64` command.

To update the BMC firmware on the local machine, do the following:

1. Install the `update-bmc-fw-<fw version>` rpm onto the machine.
2. Start the **IPMI** service if it has not already been started:

```
service ipmi start
```

3. Run the command below:

```
updatefw.x86_64 -f /usr/local/firmware/<firmware>.bin
```

Where `<firmware>` is:

`ubsim<BMC FW version>` for a **SIMSO** board.

`ugsim<BMC FW version>` for a **SIMSO+** (with **KVM**) board.

4. To initialize the **Sensor Data Repository (SDR)** on the local machine:

```
sdrload /usr/local/firmware/<platform>-sdr.dat
```

Where `<platform>` equals either `r421`, `r422` (for **NovaScale R422** and **R422 E1** machines) or `R423`.

To update the BMC firmware on a remote machine, do the following:

1. Install the `update-bmc-fw-<fw version>` rpm onto the local machine.
2. Run the command below:

```
updatefw.x86_64 -i [IP Address] -u ADMIN -p ADMIN  
-f /usr/local/firmware/<firmware>.bin
```

Where `<firmware>` is:

`ubsim<BMC FW version>` for a **SIMSO** board.

`ugsim<BMC FW version>` for a **SIMSO+** (with **KVM**) board.

3. To initialize the SDR on the remote machine:

```
sdrload /usr/local/firmware/<platform>-sdr.dat <BMC IP Address>
```

where **<platform>** equals either r421, r422 (for **NovaScale** R422 and R422 E1 machines) or R423.

Usage:

```
updatefw.x86_64 -f [Firmware File]
```

```
updatefw.x86_64 -i [IP Address] -u [Usr] -p [Pwd] -f [Firmware File]
```

```
sdrload <SDR file> [<bmc ipaddr> [<user name> <user passwd>]]
```

SDR file SDR file provided by sdredit command.

bmc ipaddr The BMC address of remote machine.
If no address is provided, the local SDR repository is updated.

user name BMC user name.

user passwd BMC user password.

To update the BMC firmware using the Web interface



See the **Bull NovaScale R42x AOC- SIMSO/SIMSO+ Installation and User's Guide** for more information.

4.3 Updating the BMC firmware on NovaScale R440 and R460 machines

The BMC update for these platforms is carried out using the **Bull Update BIOS CD**, which is also used to upgrade the **BIOS** and **FRUs**, and is available from the Bull support site. Follow the instructions provided with the CD.

4.4 Reconfiguring the BMC on R4xx machines

The **BMCs** are configured in the factory before the machines are delivered. However it may be necessary to reconfigure the **BMC** to setup a new **IP** address or when the firmware is updated. Follow the steps below to do this:

1. Install the **update-bmc-fw** rpm onto the machine.
2. Configure the **LAN** and **SOL** access to the **BMC**, with the default user name, **administrator**, and default password, **administrator**:

- For the local **BMC** of the machine, run the command:

```
bmc_init_param -b <BMC IP address> -m <BMC net mask>
```

- For a remote **BMC** on a machine accessible through **SSH**, run the command:

```
bmc_init_param -b <BMC IP address> -m <BMC net mask> -s <remote machine IP>
```

Chapter 5. Updating the firmware for the InfiniBand switches

Voltaire switches should be properly configured to ensure maximum performance. For example, **Voltaire** switch firmware version 00.08.06 ASIC does not utilise Double Data Rate transfer for those links which include **Mellanox** cards and should be upgraded. The **Voltaire** switch firmware upgrade procedure is described below.

5.1 Checking which Firmware Version is running

Go to the **utilities** menu as follows:

```
ssh enable@switchname
```

```
-----  
enable@switchname's password: voltaire  
Welcome to Voltaire Switch switchname  
Connecting  
-----
```

```
switchname # utilities  
switchname (utilities)#
```

Once in the **utilities** menu, check which firmware version is installed:

```
switchname(utilities)# firmware_verify_anafa_II
```

```
-----  
Scan Fabric  
Default fw_version is 00.08.06  
-----
```

5.2 Configuring FTP for the firmware upgrade

If the switch firmware requires an upgrade, the FTP options for the switch will need to be set. These may already be in place following the initial Installation and Configuration of the cluster. If not, they are put into place as follows:

5.2.1 Installing the FTP Server

To install the FTP server (**vsftpd**), proceed as follows:

```
rpm -ivh /<path_to_vsftpd-<version>-<arch>.rpm
```

By default, the **vsftpd** daemon will not allow root access to the FTP server. For security reasons, it is advised to create a dedicated user for this purpose. However, if you wish to enable root access to the FTP server, **vsftpd** can be enabled to allow this as follows:

1. Edit **/etc/vsftpd.ftpusers** file and comment out the line that starts by root, as shown below:

```
-----  
# Users that are not allowed to login via ftp  
# root  
Bin  
-----
```

2. Edit **/etc/vsftpd.ftpuser_list** and comment out the line that starts by root, as shown below:

```
-----  
/etc/vsftpd.user_list  
# vsftpd userlist  
# If userlist_deny=NO, only allow users in this file  
# If userlist_deny=YES (default), never allow users in this file, and  
# do not even prompt for a password.  
# Note that the default vsftpd pam config also checks  
/etc/vsftpd.ftpusers  
# for users that are denied.  
# root  
bin  
-----
```

3. Start the **vsftpd** server as follows:

```
[root@host ~]# service vsftpd start
```

```
Starting vsftpd for vsftpd:          [ OK ]
```

4. Check that FTP is working correctly:

```
[root@host ~]# ftp host
```

```
-----  
Connected to host.  
220 (vsFTPd 2.0.1)  
530 Please login with USER and PASS.  
530 Please login with USER and PASS.  
KERBEROS_V4 rejected as an authentication type  
Name (host:root): root  
331 Please specify the password.
```



```
Password:
230 Login successful.
Remote system type is UNIX.
Using binary mode to transfer files.
ftp> quit
221 Goodbye.
```

5.2.2 Configuring the FTP server options for the InfiniBand switch

Enter the FTP configuration menu as follows:

```
ssh enable@switchname
```

```
enable@switchname's password: voltaire
Welcome to Voltaire Switch switchname
connecting
```

```
switchname # config
switchname (config)# ftp
switchname (config-ftp)#
```

The following settings define the node 172.20.0.102 as the FTP server. The switch logs onto this server using Joe's account using the 'yummy' password.

```
switchname (config-ftp)# server 172.20.0.102
switchname (config-ftp)# username joe
switchname (config-ftp)# password yummy
```

Once FTP is set-up on the switch, make sure the FTP server is running on the Management Node:

```
ftp host
```

If ftp fails to connect to the host (as in the example above), it probably means that the FTP server has not been installed on the host.

```
ftp: connect: Connection refused
ftp> quit
```

5.3 Upgrading the firmware

In the following example, it is assumed that the end user stored the firmware in the existing `/path/to/firmware` directory.

1. Extract the firmware archive to the `/path/to/firmware` directory as follows:

```
cd /path/to/firmware
tar -xvf Ver_10.06_fw.1.0.0.tar
```

```
-----
voltaire_fw_images.tar
voltaire_fw_ini.tar
howto_upgrade_voltaire_switch.txt
-----
```

2. Once the firmware has been extracted, log-on to the switch and proceed with the upgrade.

- a. Upgrading the firmware for the whole switch:

```
[user@host ~]# ssh enable@switchname
```

```
-----
enable@switchname's password: voltaire
Welcome to Voltaire Switch switchname
Connecting
-----
```

```
switchname # update firmware chassis /<path_to_firmware>
```

- b. Upgrading the firmware for a specific line-board (line board 4 in the example below):

```
[user@host ~]# ssh enable@switchname
```

```
-----
enable@switchname's password: voltaire
Welcome to Voltaire Switch switchname
connecting
-----
```

```
switchname # update firmware line 4 /<path_to_firmware>
```

- c. Upgrading a fabric board (fabric board number 2 in the example below):

```
[user@host ~]# ssh enable@switchname
```

```
-----
enable@switchname's password: voltaire
Welcome to Voltaire Switch switchname
Connecting
-----
```

```
switchname # update firmware spine 2 /path/to/firmware
```



Note:

Whenever a line board or a fabric board is replaced, always ensure that is using the correct firmware.

3. Check that the firmware has upgraded correctly by running the **firmware_verify_anafa_II** command.

```
switchname(utilities)# firmware_verify_anafa_II
```


Chapter 6. Updating the firmware for the MegaRAID card

The **MegaRAID SAS** driver for the **8408E** card is included in the **BAS5 for Xeon** delivery. The **MegaRAID** card will be detected and the driver for it installed automatically during the installation of the **BAS5 for Xeon** software suite.

The **MegaCLI** tool used to update the firmware for the **MegaRAID** card and is available on the **Bull** support CD. The latest firmware file should be downloaded from the **LSI** web site.

Follow the procedure described below to update the firmware:

1. Check the version of the firmware already installed by running the command:

```
/opt/MegaCli -AdpAllInfo -a0
```

This will provide full version and manufacturing date details for the firmware, as shown in the example below:

```
-----
Adapter #0
=====
                Versions
                =====
Product Name    : MegaRAID SAS 8408E
Serial No      : P088043006
FW Package Build: 5.0.1-0053
                Mfg. Data
                =====
Mfg. Date      : 01/16/07
Rework Date    : 00/00/00
Revision No    : (

                Image Versions In Flash:
                =====
Boot Block Version : R.2.3.2
BIOS Version       : MT25
MPT Version        : MPTFW-01.15.20.00-IT
FW Version         : 1.02.00-0119
WebBIOS Version   : 1.01-24
Ctrl-R Version    : 1.02-007

                Pending Images In Flash
                =====
None
-----
```



Note:

The following **MegaRAID** card details are also provided when the **AdpAllInfo** command runs: PCI slot info, Hardware Configuration, Settings and Capabilities for the card, Status, Limitations, Devices present, Virtual Drive and Physical Drive Operations supported by the card, Error Counters, and Default Card Settings.

2. Decompress and extract the firmware by running the command below:

```
unzip ~/lsi/5.1.1-0054_SAS_FW_Image_1.03.60-0255.zip
```

```
-----  
Archive:  /root/lsi/5.1.1-0054_SAS_FW_Image_1.03.60-0255.zip  
  inflating: sasfw.rom  
  inflating: 5.1.1-0054_SAS_FW_Image_1.03.60.0255.txt  
  extracting: DOS_MegaCLI_1.01.24.zip
```

3. Update the firmware using the MegaCLI tool using the command below:

```
/opt/MegaCli -adpflash -f sasfw.rom -a0
```

```
-----  
Adapter 0: MegaRAID SAS 8408E  
Vendor ID: 0x1000, Device ID: 0x0411  
  
FW version on the controller: 1.02.00-0119  
FW version of the image file: 1.03.60-0255  
Flashing image to adapter...  
Adapter 0: Flash Completed.
```

4. Reboot the server so that the new firmware is activated for the card.

Chapter 7. Managing the BIOS on NovaScale R4xxx Machines

This chapter describes how to update the BIOS on NovaScale R4XX machines. It also defines the recommended settings for the BIOS parameters for these machines.

7.1 Updating the BIOS on NovaScale R421, R422, R422 E1 and R423

This section describes how to update the motherboard BIOS of a NovaScale R421, R422, R422 E1 or R423 machine.

Install the `bios-<platform>-<bios version>` rpm corresponding to your platform and to the new BIOS release. The corresponding BIOS DOS image `<BIOS>.IMG` is installed in `/usr/local/firmware`.



Warning:

- Ensure that the BIOS version corresponding to your platform is used.
- The BIOS upgrade **MUST NOT** be interrupted whilst it is in course of operation.
- If the BIOS does not work, a new BIOS chip must be ordered.

To install a new BIOS locally:

1. Copy the `<BIOS>.IMG` file onto a USB key:

```
dd if=/usr/local/firmware/<BIOS>.IMG of=/dev/sd<your USB device>
```

2. Insert the key and reboot the machine.
The `autoexec` file contained in the DOS file automatically starts the BIOS update.
Wait for the BIOS installation to finish.
3. Remove the USB key.
4. Restart the machine.

To install a new BIOS on a remote machine using PXE:



Note:

The remote machine must be configured to boot via **PXE** on the server. The server must be configured as a TFTP server.

1. Install the `update-bios` rpm on the server.

2. If the remote machine is accessible using IPMI run this command on the server:

```
update-bios <remote IP address> /usr/local/firmware/<BIOS>.IMG <BMC IP address>
```

or if the server can connect to the remote machine using **ssh** then run this command:

```
update-bios <remote IP address> /usr/local/firmware/<BIOS>.IMG
```

3. The **update-bios** command returns after the **BIOS** update is completed on the remote machine.

Usage:

```
update-bios <ipaddr> <bios image> [ <bmc ipaddr> [<user name> <user passwd>] ]
```

ipaddr network address of remote machine to have **BIOS** update

bios image local path to the **BIOS** DOS image file

bmc ipaddr **BMC** address of remote machine

user name **BMC** user name

user passwd **BMC** user password

To install a new BIOS on a remote machine using the Web interface (R421, R422, R422 E1 and R423):

On the R421, R422, R422 E1 and R423 platforms, it is possible to access the BMC through the Web interface (see Chapter 4).

From the administration node:

1. Start the Firefox navigator:

```
/usr/local/firefox/firefox
```

2. In the navigation bar, type the URL of the remote BMC:

```
http://<BMC IP addr>
```

and login to the BMC.

3. Select the **Virtual Media** button and upload the BIOS image (**/usr/local/firmware/<BIOS>.IMG**) corresponding to the machine.
4. Select the **Console Button** to access the console of the remote system.
5. Restart the remote system. The BIOS DOS image will boot and flash the new BIOS. The progression can be followed in the console window.
6. When the BIOS update is ended, the DOS prompt appears in the console window.

7. Select the **Virtual Media** button and discard the BIOS DOS image.
8. Reset the machine using the **Remote Control** button.

7.2 Updating the BIOS on NovaScale R440 or R460

The BIOS update on these platforms is done through the Bull Update BIOS CD that allows upgrading the BIOS, BMC firmware and FRUs. Please follow the instructions provided with the CD.

7.3 BIOS Parameter Settings for NovaScale Rxxx Nodes

The BIOS parameter settings for the NovaScale R421, R421 E1, R422, R422 E1 Compute Nodes and R440, R460, R423 Service Nodes will normally be configured in the factory before the machines are delivered. However, if the cluster set up is changed, the following settings can be used to reset the machines back to their original state.



Notes:

- The settings shown in the tables are the default values. The parameter values that have to be changed for HPC are indicated in green and bold.
- Some of these settings, for example for the storage, will vary according to the cluster and will differ from the settings shown in the tables and screen grabs.

7.3.1 Examples

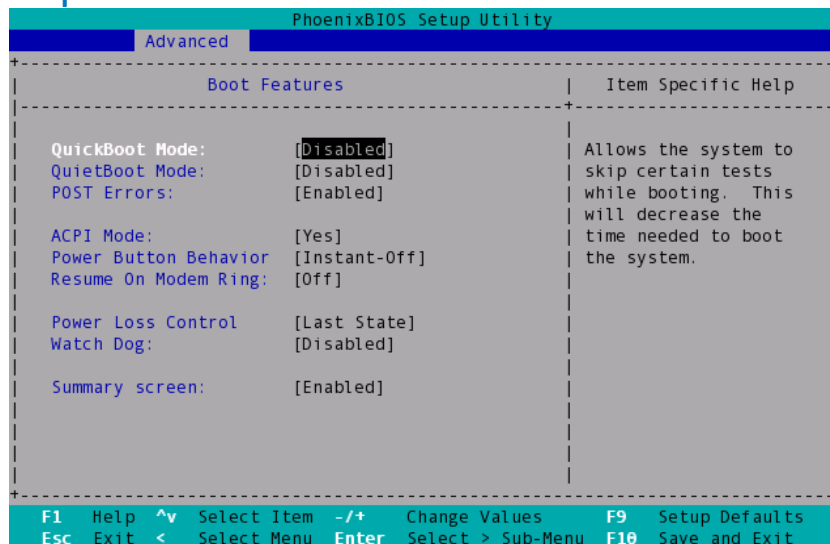


Figure 7-1. Example BIOS parameter setting screen for NovaScale R421

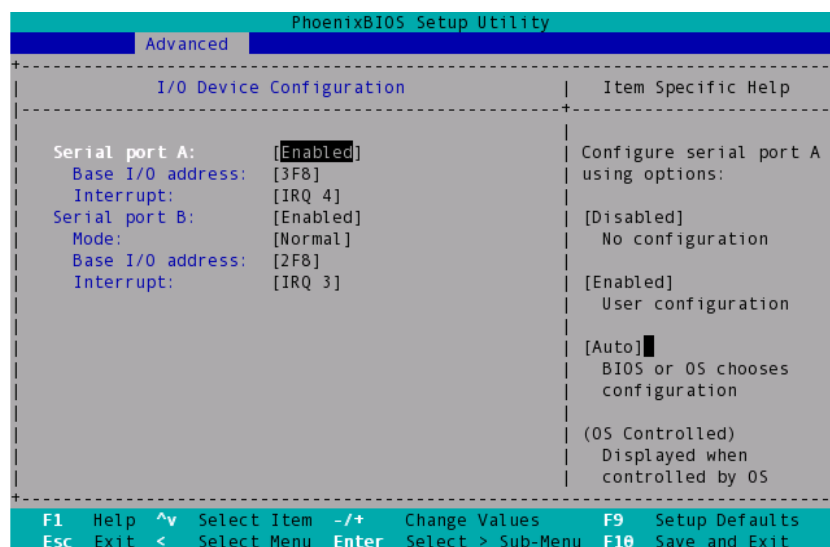


Figure 7-2. Example BIOS parameter setting screen for NovaScale R422

7.3.2 NovaScale R421 BIOS Settings

mainboard
BIOS

X7DBR-8/X7DBR-I
1.3c

R421

BIOS setup section		parameter	value	
Main	System Time		<Current local time>	
	System Date		<Current date>	
	Legacy diskette A:		Disabled	
	Serial ATA		Enabled	
	Native Mode Operation		Serial ATA	
	SATA Controller Mode Option		Compatible	
Advanced	Boot Features	QuickBoot Mode	Disabled	
		QuietBoot Mode	Disabled	
		POST Errors	Disabled	
		ACPI Mode	Yes	
		Power Button Behaviour	Instant-Off	
		Resume On Modem Ring	Off	
		Power Loss Control	Last State	
		Watch Dog	Disabled	
		Summary screen	Disabled	
	Memory Cache	Cache System BIOS area		Write Protect
		Cache Video BIOS area		Write Protect
		Cache Base 0-512k		Write Back
		Cache Base 512k-640k		Write Back
		Cache Extended Memory Area		Write Back
		Discrete MTRR Allocation		Disabled
	PCI Configuration	Onboard G-LAN1 OPROM Configure		Enabled
		Onboard G-LAN2 OPROM Configure		Disabled
		Default Primary Video Adapter		Onboard
		Emulated IRQ Solution		Disabled
		PCI-e I/O Performance		Payload 256B
		PCI Parity Error Forwarding		Disabled
		ROM Scan Ordering		Onboard First
		PCI Fast Delayed Transaction		Disabled
		Reset Configuration Data		No
		Frequency for PCI-X#1-#2/MASS		Auto
		SLOT1 PCI-X 100MHz	Option ROM Scan	Enabled
			Enable Master	Enabled
Latency Timer			Default	
SLOT2 PCI-X 100MHz ZCR		Option ROM Scan	Enabled	
		Enable Master	Enabled	
		Latency Timer	Default	
SLOT2 PCI-X 100MHz ZCR		Option ROM Scan	Enabled	
		Enable Master	Enabled	
	Latency Timer	Default		
SLOT3 PCI-Exp x8	Option ROM Scan	Enabled		
	Enable Master	Enabled		
	Latency Timer	Default		
SLOT4 PCI-Exp x8	Option ROM Scan	Enabled		
	Enable Master	Enabled		

BIOS setup section	parameter	value
	Latency Timer	Default
	Option ROM Scan	Enabled
	Enable Master	Enabled
	SLOT5 PCI-Exp x8 Latency Timer	Default
	Large Disk Access Mode	DOS
Advanced Chipset Control	SERR signal condition	Single bit
	4GB PCI Hole Granularity	256 MB
	Memory Branch Mode	Interleave
	Branch 0 Rank Interleave	« 4:1 »
	Branch 0 Rank Sparing	Disabled
	Branch 1 Rank Interleave	« 4:1 »
	Branch 1 Rank Sparing	Disabled
	Enhanced x8 Detection	Enabled
	High Bandwidth FSB	Enabled
	High Temp DRAM OP	Disabled
	AMB Thermal Sensor	Disabled
	Thermal Throttle	Disabled
	Global Activation Throttle	Disabled
	Crystal Beach Feature	Enabled
	Route Port 80h cycles to	LPC
	Clock Spectrum Feature	Disabled
	High Precision Event Timer	No
	USB Function	Enabled
	Legacy USB Support:	Enabled
Advanced Processor Options	Frequency Ratio	Default]
	Core Multi-Processing	Enabled
	Machine Checking	Enabled
	Thermal Management 2	Enabled
	C1 Enhanced Mode	Disabled
	Execute Disable Bit	Enabled
	Adjacent Cache Line Prefetch	Enabled
	Hardware Prefetcher	Enabled
	Direct Cache Access	Disabled
	Intel(R) Virtualization Technology	Disabled
	Intel EIST support	Disabled]
I/O Device Configuration	KBC Clock Input	12MHz
	Serial port A	Enabled]
	Base I/O address (Serial port A)	3F8
	Interrupt (Serial port A)	IRQ 4
	Serial port B	Enabled
	Mode	Normal
	Base I/O address (Serial port B)	2F8
	Interrupt (Serial port B)	IRQ 3
	Floppy disk controller	Enabled
	Base I/O address	Primary
DMI Event Logging	Event Logging	Enabled
	ECC Event Logging	Enabled
Console Redirection	Com Port Address	On-board COM B
	Baud Rate	115.2K
	Console Type	VT100+

BIOS setup section		parameter	value
		Flow Control	None
		Console connection	Direct
		Continue C.R. after POST	On
	Hardware Monitor	CPU Temperature Threshold	75oC
		Fan Speed Control Modes	1)Disable(Full spe
	IPMI	System Event Logging	Enabled
		Clear System Event Log	Disabled
		SYS Firmware Progress	Disabled
		BIOS POST Errors	Enabled
		BIOS POST Watchdog	Disabled
OS boot Watchdog		Disabled	
Timer for loading OS (min)		10	
	Time out action	No Action	
Security		Supervisor Password Is	Clear
		User Password Is	Clear
		Password on boot	Disabled
Boot		1	USB FDC
		2	USB CDROM
		3	USB KEY
		4	PCI BEV: IBA GE Slot 0400 v1236
		5	IDE 4: WDC WD1600YS-01SHB1-(S2)
		6	
		7	
		8	

7.3.3 NovaScale R421 E1 BIOS Settings

motherboard
BIOS

S5400SF

S5400.86B.06.00.0023

R421 E1

BIOS setup section		parameter		value
Main	Quiet Boot			Disabled
	Post Error Pause			Disabled
	System Date			<Current date>
	System Time			<Current local time>
	Serial ATA			Enabled
Advanced	Processor Configuration	Enhanced Intel Speedstep		Enabled
		Core Multi-Processing		Enabled
		Intel(R) Virtualization Technology		Disabled
		Intel VT for Directed I/O		Disabled
		Simulated MSI support		Disabled
		Execute Disable Bit		Disabled
		Hardware Prefetcher		Enabled
		Adjacent Cache Line Prefetch		Enabled
		IOAT2 enable		Enabled
	Processor Retest		Disabled	
Memory Configuration	Memory RAS & performances	Memory RAS configuration	RAS Disabled	
		Snoop Filter	Enabled	
ATA Configuration	FSB High Bandwith Optimisation		Enabled	
	Onboard PATA Controller		Enabled	
	Onboard SATA Controller		Enabled	
	SATA Mode		Enhanced	
	AHCI Mode		Disabled	
Serial Ports Configuration	Configure SATA as RAID		Disabled	
	Configure SAS as SW RAID		Disabled	
	Serial A Enable		Enabled	
	Address		3F8	
	IRQ		4	
	Serial B Enable		Enabled	
USB Configuration	Address		2F8	
	IRQ		3	
	USB Controller		Enabled	
	Legacy USB Support:		Enabled	
	Port 60/64 emulation		Disabled	
	Device reset Timeout		20 s	
	Storage Emulation		Auto	
PCI Configuration	USB 2.0 Controller		Enabled	
	Memory mapped I/O start addr		2.00GB	
	Memory mapped I/O above 4GB		Disabled	
	Onboard video		Enabled	
	Dual Monitor Video		Disabled	
	Onboard NIC1 ROM		Enabled	
	Onboard NIC2 ROM		Disabled	
	I/O Module NIC ROM		Disabled	
	Intel IOAT		Enabled	
	System accoustic & Perf		Throttling mode	Closed Loop
Security	Administrator password		Not Installed	

BIOS setup section	parameter		value
	User Password		Not Installed
	Front panel lockout		Disabled
Server Management	Assert NMI on SERR		Enabled
	Assert NMI on PERR		Enabled
	Resume on AC Power Loss		Last state
	Windows hw error architecture		Enabled
	FRB-2 Enable		Enabled
	OS boot Watchdog		Disabled
	BMC PLUG & Play detection		Disabled
	Console Redirection	Console Redirection	Serial B
		Flow Control	None
		Baud Rate	115.2k
	Terminal Type	VT100+	
	Legacy OS Redirection	Disabled	
Boot Options	Boot Timeout		0
	Boot Option #1		PATA DVD (if present)
	Boot Option #2		IBA GE Slot 600 v1240
	Boot Option #3		SATA 0
	Boot Option #4		EFI shell
	Hard Disk Order	hard disk #1	SATA 0
		hard disk #2	SATA 1
		hard disk #3	SATA 2
	Network Device Order	network device #1	IBA GE Slot 600 v1240
		network device #2	Disabled
Boot Option Retry		Disabled	

7.3.4 NovaScale R422 BIOS Settings

motherboard
BIOS

X7DBT/X7DGT
1.3c

R422

BIOS setup section		parameter	value	
Main		System Time	<Current local time>	
		System Date	<Current date>	
		Serial ATA	Enabled	
		Native Mode Operation	Serial ATA	
		SATA Controller Mode Option	Compatible	
Advanced	Boot Features	QuickBoot Mode	Disabled	
		QuietBoot Mode	Disabled	
		POST Errors	Disabled	
		ACPI Mode	Yes	
		Power Button Behaviour	Instant-Off	
		Resume On Modem Ring	Off	
		Power Loss Control	Last State	
		Watch Dog	Disabled	
		Summary screen	Disabled	
		Memory Cache	Cache System BIOS area	Write Protect
	Cache Video BIOS area		Write Protect	
	Cache Base 0-512k		Write Back	
	Cache Base 512k-640k		Write Back	
	Cache Extended Memory Area		Write Back	
	Discrete MTRR Allocation		Disabled	
	PCI Configuration	Onboard G-LAN1 OPROM Configure	Enabled	
		Onboard G-LAN2 OPROM Configure	Disabled	
		Default Primary Video Adapter	Onboard	
		Emulated IRQ Solution	Disabled	
		PCI-e I/O Performance	Payload 256B	
		PCI Parity Error Forwarding	Disabled	
		ROM Scan Ordering	Onboard First	
		Reset Configuration Data	No	
		SLOT1 PCI-Exp x8	Option ROM Scan	Enabled
			Enable Master	Enabled
	Latency Timer		Default	
		Large Disk Access Mode	DOS	
	Advanced Chipset Control	SERR signal condition	Single bit	
		4GB PCI Hole Granularity	256 MB	
		Memory Branch Mode	Interleave	
		Branch 0 Rank Interleave	« 4:1 »	
		Branch 0 Rank Sparing	Disabled	
		Branch 1 Rank Interleave	« 4:1 »	
Branch 1 Rank Sparing		Disabled		
Enhanced x8 Detection		Enabled		
High Bandwidth FSB		Enabled		
High Temp DRAM OP		Disabled		
AMB Thermal Sensor		Disabled		
Thermal Throttle		Disabled		
Global Activation Throttle	Disabled			

BIOS setup section	parameter	value
	Crystal Beach Feature Route Port 80h cycles to Clock Spectrum Feature High Precision Event Timer USB Function Legacy USB Support:	Enabled LPC Disabled No Enabled Enabled
Advanced Processor Options	Frequency Ratio Core Multi-Processing Machine Checking Thermal Management 2 C1 Enhanced Mode Execute Disable Bit Adjacent Cache Line Prefetch Hardware Prefetcher Direct Cache Access Intel(R) Virtualization Technology Intel EIST support	Default] Enabled Enabled Enabled Disabled Enabled Enabled Enabled Disabled Disabled Disabled
I/O Device Configuration	Serial port A Base I/O address (Serial port A) Interrupt (Serial port A) Serial port B Mode Base I/O address (Serial port B) Interrupt (Serial port B)	Enabled 3F8 IRQ 4 Enabled Normal 2F8 IRQ 3
DMI Event Logging	Event Logging ECC Event Logging	Enabled Enabled
Console Redirection	Com Port Address Baud Rate Console Type Flow Control Console connection Continue C.R. after POST	On-board COM B 115.2K VT100+ None Direct On
Hardware Monitor	CPU Temperature Threshold Fan Speed Control Modes	75oC 2 3-pin(Server)
IPMI	System Event Logging Clear System Event Log SYS Firmware Progress BIOS POST Errors BIOS POST Watchdog OS boot Watchdog Timer for loading OS (min) Time out action	Enabled Disabled Disabled Enabled Disabled Disabled 10 No Action
Security	Supervisor Password Is User Password Is Password on boot	Clear Clear Disabled
Boot	1 2 3 4 5	USB FDC USB CDROM USB KEY USB LS120: PepperC Virtual disc PCI BEV: IBA GE Slot 0400 v1236

BIOS setup section	parameter	value
	6 7 8	IDE 4: WDC WD1600YS-01SHB1-(S2)

7.3.5 NovaScale R422 E1 BIOS Settings

motherboard
BIOS

X7DWT
1.0b 7DWTC217

R422 E1

BIOS setup section		parameter	value
Main		System Time	<Current local time>
		System Date	<Current date>
		Serial ATA	Enabled
		Native Mode Operation	Serial ATA
		SATA Controller Mode Option	Compatible
Advanced	Boot Features	QuickBoot Mode	Disabled
		QuietBoot Mode	Disabled
		POST Errors	Disabled
		ACPI Mode	Yes
		Power Button Behaviour	Instant-Off
		Resume On Modem Ring	Off
		EFI OS Boot	Disabled
		Power Loss Control	Last State
		Watch Dog	Disabled
		Summary screen	Disabled
		Memory Cache	Cache System BIOS area
	Cache Video BIOS area		Write Protect
	Cache Base 0-512k		Write Back
	Cache Base 512k-640k		Write Back
	Cache Extended Memory Area		Write Back
	Discrete MTRR Allocation		Disabled
	PCI Configuration	Onboard G-LAN1 OPROM Configure	Enabled
		Onboard G-LAN2 OPROM Configure	Disabled
		Option ROM Re-Placement	Disabled
		PCI Parity Error Forwarding	Disabled
		PCI Fast Delayed Transaction	Disabled
		Reset Configuration Data	No
		SLOT1 PCI-Exp x16	Option ROM Scan
		Enable Master Latency Timer	Enabled
			Default
		Large Disk Access Mode	DOS
	Advanced Chipset Control	SERR signal condition	Single bit
Clock Spectrum Feature		Disabled	
Intel VT for Directed I/O (VT-d)		Disabled	
4GB PCI Hole Granularity		256 MB	
Memory Voltage		Auto	
Memory Branch Mode		Interleave	
Branch 0 Rank Interleave		« 4:1 »	
Branch 0 Rank Sparing		Disabled	
Branch 1 Rank Interleave		« 4:1 »	
Branch 1 Rank Sparing		Disabled	
Enhanced x8 Detection		Enabled	
Demand Scrub		Enabled	
High Temp DRAM OP		Disabled	
AMB Thermal Sensor	Disabled		

BIOS setup section	parameter	value
	Thermal Throttle Global Activation Throttle Force ITK Config Clocking Snoop Filter Crystal Beach Feature Route Port 80h cycles to High Precision Event Timer USB Function Legacy USB Support:	Disabled Disabled Disabled] Enabled Enabled LPC No Enabled Enabled
Advanced Processor Options	Frequency Ratio Core Multi-Processing Machine Checking Fast String operations Thermal Management 2 C1/C2 Enhanced Mode Execute Disable Bit Adjacent Cache Line Prefetch Hardware Prefetcher Set Max Ext CPUID = 3 Direct Cache Access Intel(R) Virtualization Technology Intel EIST support	Default] Enabled Enabled Enabled Enabled Disabled Enabled Enabled Enabled Disabled Disabled Disabled Disabled
I/O Device Configuration	KBC Clock Input Serial port A Base I/O address (Serial port A) Interrupt (Serial port A) Serial port B Mode Base I/O address (Serial port B) Interrupt (Serial port B)	12MHz Enabled 3F8 IRQ 4 Enabled Normal 2F8 IRQ 3
DMI Event Logging	Event Logging ECC Event Logging	Enabled Enabled
Console Redirection	Com Port Address Baud Rate Console Type Flow Control Console connection Continue C.R. after POST	On-board COM B 115.2K VT100+ None Direct On
Hardware Monitor	Fan Speed Control Modes	2)3-pin(Server)
IPMI	System Event Logging Clear System Event Log SYS Firmware Progress BIOS POST Errors BIOS POST Watchdog OS boot Watchdog Timer for loading OS (min) Time out action	Enabled Disabled Disabled Enabled Disabled Disabled 10 No Action
Security	Supervisor Password Is User Password Is Password on boot	Clear Clear Disabled

BIOS setup section	parameter	value
Boot	1	USB FDC
	2	USB CDROM
	3	USB KEY
	4	USB HDD
	5	USB LS120: <i>PepperC Virtual disc</i>
	6	PCI BEV: <i>IBA GE Slot 0500 v1270</i>
	7	IDE 2: <i>WDC WD1600YS-01SHB1-(S0)</i>
	8	

7.3.6 NovaScale R423 BIOS Settings

mainboard
BIOS

X7DWN+
1.0b 7DWNC217

R423

BIOS setup section		parameter	value	
Main		System Time	<Current local time>	
		System Date	<Current date>	
		Legacy diskette A:	1.44MB	
		Parallel ATA	Enabled	
		Serial ATA	Enabled	
		SATA Controller Mode Option	Enhanced	
		SATA Raid enable	Disabled	
		SATA AHCI enable	Disabled	
Advanced	Boot Features	QuickBoot Mode	Disabled	
		QuietBoot Mode	Disabled	
		POST Errors	Disabled	
		ACPI Mode	Yes	
		Power Button Behaviour	Instant-Off	
		Resume On Modem Ring	Off	
		EFI os boot	Disabled	
		Power Loss Control	Last State	
		Watch Dog	Disabled	
		Summary screen	Disabled	
	Memory Cache		Cache System BIOS area	Write Protect
			Cache Video BIOS area	Write Protect
			Cache Base 0-512k	Write Back
			Cache Base 512k-640k	Write Back
			Cache Extended Memory Area	Write Back
			Discrete MTRR Allocation	Disabled
	PCI Configuration		Onboard G-LAN1 OPROM Configure	Enabled
			Onboard G-LAN2 OPROM Configure	Disabled
			Option ROM Re-Placement	Disabled
			PCI Parity Error Forwarding	Disabled
			PCI Fast Delayed Transaction	Disabled
			Reset Configuration Data	No
			Frequency for PCI#1-#2	Auto
		SLOT0 PCI-U X8	Option ROM Scan	Enabled
			Enable Master	Enabled
			Latency Timer	Default
			SLOT1 PCI-X 133MHz	Option ROM Scan
Enable Master				Enabled
Latency Timer	Default			
SLOT2 PCI-X 133MHz	Option ROM Scan	Enabled		
	Enable Master	Enabled		
	Latency Timer	Default		
SLOT3 PCI-Exp x8	Option ROM Scan	Enabled		
	Enable Master	Enabled		
	Latency Timer	Default		
SLOT4 PCI-Exp x4	Option ROM Scan	Enabled		
	Enable Master	Enabled		

BIOS setup section	parameter	value
	Latency Timer	Default
	SLOT5 PCI-Exp x8	Option ROM Scan Enabled Enable Master Enabled Latency Timer Default
	SLOT6 PCI-Exp x8	Option ROM Scan Enabled Enable Master Enabled Latency Timer Default
	Large Disk Access Mode	DOS
Advanced Chipset Control	SERR signal condition	Single bit
	Clock Spectrum Feature	Disabled
	Intel VT for Directed I/O	Disabled
	4GB PCI Hole Granularity	256 MB
	Memory Voltage	Auto
	Memory Branch Mode	Interleave
	Branch 0 Rank Interleave	« 4:1 »
	Branch 0 Rank Sparing	Disabled
	Branch 1 Rank Interleave	« 4:1 »
	Branch 1 Rank Sparing	Disabled
	Enhanced x8 Detection	Enabled
	Demand Scrub	Enabled
	High Temp DRAM OP	Disabled
	AMB Thermal Sensor	Disabled
	Thermal Throttle	Disabled
	Global Activation Throttle	Disabled
	Force ITK Config Clocking	Disabled
	Snoop Filter	Enabled
	Crystal Beach Feature	Enabled
	Route Port 80h cycles to	LPC
	Clock Spectrum Feature	Disabled
	High Precision Event Timer	No
	USB Function	Enabled
	Legacy USB Support:	Enabled
Advanced Processor Options	Frequency Ratio	Default]
	Core Multi-Processing	Enabled
	Machine Checking	Enabled
	Fast String operations	Enabled
	Thermal Management 2	Enabled
	C1/C2 Enhanced Mode	Disabled
	Execute Disable Bit	Enabled
	Adjacent Cache Line Prefetch	Enabled
	Hardware Prefetcher	Enabled
	Set Max Ext CPUID = 3	Disabled
	Direct Cache Access	Disabled
	Intel(R) Virtualization Technology	Disabled
	Intel EIST support	Disabled]
I/O Device Configuration	KBC Clock Input	12MHz
	Serial port A	Enabled]
	Base I/O address (Serial port A)	3F8
	Interrupt (Serial port A)	IRQ 4
	Serial port B	Enabled
	Mode	Normal
	Base I/O address (Serial port B)	2F8

BIOS setup section	parameter	value
	Interrupt (Serial port B) Parallel Port Floppy disk controller Base I/O address	IRQ 3 Disabled Enabled Primary
	DMI Event Logging	Event Logging ECC Event Logging Enabled Enabled
	Console Redirection	Com Port Address Baud Rate Console Type Flow Control Console connection Continue C.R. after POST On-board COM B 115.2K VT100+ None Direct On
	Hardware Monitor	Fan Speed Control Modes 1)Disable(Full speed)
	IPMI	System Event Logging Clear System Event Log SYS Firmware Progress BIOS POST Errors BIOS POST Watchdog OS boot Watchdog Timer for loading OS (min) Time out action Enabled Disabled Disabled Enabled Disabled Disabled 10 No Action
	Security	Supervisor Password Is User Password Is Password on boot Clear Clear Disabled
Boot	1 2 3 4 5 6 7 USB FDC USB KEY IDE CD: Optiarc DVD RW USB CDROM USB LS120: PepperC Virtual disk PCI BEV: IBA GE Slot 0800 v1270 IDE 2: WDC WD2500YS-01SHB1-(S0)	

7.3.7 NovaScale R440 SATA BIOS Settings

System part number N8100-1241E
 BIOS 5S36

R440 SATA

Motherboard Jumper settings

JSASRAID2

1-2 (RAID disable)

BIOS setup section		parameter		value
Main	System Time			<Current local time>
	System Date			<Current date>
	Hard Disk Pre-Delay			Disabled
	Primay IDE Master	Type:		Auto
		32 Bit I/O		Enabled
	Processor Settings	Processor Retest		No
	Execute Disable Bit		Disabled	
	Intel(R) Virtualization Tech		Disabled	
	Enhanced Intel SpeedStep(R) Tech.		Disabled	
	Language		English (US)	
Advanced	Memory Configuration	Memory Retest		No
		Extended RAM Step		Disabled
		Memory RAS Feature		Interleave
		Sparing		Disabled
	PCI Configuration	Onboard Video Controller	VGA Controller	Enabled
			Onboard VGA Option ROM Scan	Auto
		Onboard LAN	LAN Controller	Enabled
			LAN1 Option ROM Scan	Enabled
			LAN2 Option ROM Scan	Enabled
	PCI Slot 1B Option ROM		Enabled	
	PCI Slot 1C Option ROM		Enabled	
	Peripheral Configuration	Serial port A	Base I/O address	3F8
			Interrupt	IRQ 4
		Serial port B	Base I/O address	2F8
			Interrupt	IRQ 3
		USB 2.0 Controller		Enabled
		Parallel ATA		Enabled
		Serial ATA		Enabled
	SATA Controller Mode Option		Compatible	
	Advanced Chipset Control	Multimedia Timer		Enabled
Intel(R) I/OAT		Enabled		
Wake On LAN/PME		Enabled		
Wake On Ring		Disabled		
Wake On RTC Alarm		Disabled		
	Boot-time Diagnostic Screen		Enabled	
	Reset Configuration Data		No	
	NumLock		On	
	Memory/Processor Error		Boot	
Security	Supervisor Password Is		Clear	
	User Password Is		Clear	
	Password on boot		Disabled	

BIOS setup section		parameter	value	
		Fixed disk boot sector	<i>Normal</i>	
		Power Switch Inhibit:	<i>Disabled</i>	
Server	Console Redirection	BIOS Redirection Port	Serial Port B	
		ACPI Redirection Port	<i>Disabled</i>	
		Baud Rate	115.2K	
		Flow Control	None	
		Terminal Type	<i>VT100+</i>	
		Remote Console Reset	Enabled	
			Assert NMI on PERR	<i>Enabled</i>
			Assert NMI on SERR	<i>Enabled</i>
			FRB-2 Policy	<i>Retry 3 Times</i>
			Boot Monitoring	<i>Disabled</i>
			Boot Monitoring Policy	<i>Retry 3 Times</i>
			Thermal Sensor	<i>Enabled</i>
			BMC IRQ	<i>IRQ 11</i>
			Post Error Pause	<i>Enabled</i>
			AC-LINK	<i>Last State</i>
			Power On Delay Time	<i>0</i>
			Platform Event Filtering	<i>Enabled</i>
Boot		1	USB FDC	
		2	USB CDROM	
		3	USB KEY	
		4	IDE CD	
		5	PCI BEV: IBA GE Slot 0C00 v1236	
		6	IDE HDD: HDT722525DLA380-(S1)	
		7		
		8		

7.3.8

NovaScale R440 SAS BIOS Settings

System
BIOS

part number N8100-1243E
5S46

R440 SAS

Motherboard Jumper settings

JSASRAID2

1-2 (RAID disable)

BIOS setup section		parameter		value
Main	System Time			<Current local time>
	System Date			<Current date>
	Hard Disk Pre-Delay			Disabled
	Processor Settings	Processor Retest		No
		Execute Disable Bit		Disabled
Intel(R) Virtualization Tech		Disabled		
Enhanced Intel SpeedStep(R) Tech.		Disabled		
Language			English (US)	
Advanced	Memory Configuration	Memory Retest		No
		Extended RAM Step		Disabled
		Memory RAS Feature		Interleave
		Sparing		Disabled
	PCI Configuration	Onboard Video Controller	VGA Controller	Enabled
			Onboard VGA Option ROM Scan	Auto
		Onboard LAN	LAN Controller	Enabled
			LAN1 Option ROM Scan	Enabled
	PCI Slot 1B Option ROM		Enabled	
	PCI Slot 1C Option ROM		Enabled	
	Peripheral Configuration	Serial port A	Base I/O address	3F8
			Interrupt	IRQ 4
		Serial port B	Base I/O address	2F8
			Interrupt	IRQ 3
		USB 2.0 Controller		Enabled
Parallel ATA		Enabled		
Serial ATA		Enabled		
SATA Controller Mode Option		Compatible		
Advanced Chipset Control	Multimedia Timer		Enabled	
	Intel(R) I/OAT		Enabled	
	Wake On LAN/PME		Enabled	
	Wake On Ring		Disabled	
	Wake On RTC Alarm		Disabled	
Boot-time Diagnostic Screen		Enabled		
Reset Configuration Data		No		
NumLock		On		
Memory/Processor Error		Boot		
Security	Supervisor Password Is		Clear	
	User Password Is		Clear	
	Password on boot		Disabled	
	Fixed disk boot sector		Normal	
Power Switch Inhibit:		Disabled		
Server	Console Redirection	BIOS Redirection Port	Serial Port B	

BIOS setup section	parameter	value
	ACPI Redirection Port Baud Rate Flow Control Terminal Type Remote Console Reset	<i>Disabled</i> 115.2K None VT100+ Enabled
	Assert NMI on PERR Assert NMI on SERR FRB-2 Policy Boot Monitoring Boot Monitoring Policy Thermal Sensor BMC IRQ Post Error Pause AC-LINK Power On Delay Time Platform Event Filtering	<i>Enabled</i> <i>Enabled</i> <i>Retry 3 Times</i> <i>Disabled</i> <i>Retry 3 Times</i> <i>Enabled</i> <i>IRQ 11</i> <i>Enabled</i> <i>Last State</i> <i>20</i> <i>Enabled</i>
Boot	1 2 3 4 5 6 7 8	USB FDC USB CDROM USB KEY IDE CD PCI BEV: IBA GE Slot 0C00 v1236 PCI SCSI

7.3.9 NovaScale R460 BIOS Settings

System part number N8100-1247E
 BIOS 5S46

R460

Motherboard Jumper settings

JSASRAID2

1-2 (RAID disable)

BIOS setup section		parameter		value	
Main	System Time		<Current local time>		
	System Date		<Current date>		
	Hard Disk Pre-Delay		Disabled		
	Processor Settings	Processor Retest		No	
		Execute Disable Bit		Disabled	
Intel(R) Virtualization Tech		Disabled			
Enhanced Intel SpeedStep(R) Tech.		Disabled			
Language		English (US)			
Advanced	Memory Configuration	Memory Retest		No	
		Extended RAM Step		Disabled	
		Memory RAS Feature		Interleave	
		Sparing		Disabled	
	PCI Configuration	Onboard Video Controller	VGA Controller		Enabled
			Onboard VGA Option ROM Scan		Auto
		Onboard LAN	LAN Controller		Enabled
			LAN1 Option ROM Scan		Enabled
			LAN2 Option ROM Scan		Enabled
		PCI Slot 1B Option ROM		Enabled	
		PCI Slot 1C Option ROM		Enabled	
	PCI Slot 2B Option ROM		Enabled		
	PCI Slot 2C Option ROM		Enabled		
	PCI Slot 3B Option ROM		Enabled		
	PCI Slot 3C Option ROM		Enabled		
	Peripheral Configuration	Serial port A	Base I/O address		3F8
			Interrupt		IRQ 4
Serial port B		Base I/O address		2F8	
		Interrupt		IRQ 3	
USB 2.0 Controller		Enabled			
Parallel ATA		Enabled			
Serial ATA		Enabled			
SATA Controller Mode Option		Compatible			
Advanced Chipset Control	Multimedia Timer		Enabled		
	Intel(R) I/OAT		Enabled		
	Wake On LAN/PME		Enabled		
	Wake On Ring		Disabled		
	Wake On RTC Alarm		Disabled		
	Boot-time Diagnostic Screen		Enabled		
	Reset Configuration Data		No		
	NumLock		On		
	Memory/Processor Error		Boot		
	Supervisor Password Is		Clear		
Security					

BIOS setup section		parameter	value	
		User Password Is	<i>Clear</i>	
		Password on boot	<i>Disabled</i>	
		Fixed disk boot sector	<i>Normal</i>	
		Power Switch Inhibit:	<i>Disabled</i>	
Server	Console Redirection	BIOS Redirection Port	Serial Port B	
		ACPI Redirection Port	<i>Disabled</i>	
		Baud Rate	115.2K	
		Flow Control	None	
		Terminal Type	<i>VT100+</i>	
		Remote Console Reset	Enabled	
			Assert NMI on PERR	<i>Enabled</i>
			Assert NMI on SERR	<i>Enabled</i>
			FRB-2 Policy	<i>Retry 3 Times</i>
			Boot Monitoring	<i>Disabled</i>
			Boot Monitoring Policy	<i>Retry 3 Times</i>
			Thermal Sensor	<i>Enabled</i>
			BMC IRQ	<i>IRQ 11</i>
			Post Error Pause	<i>Enabled</i>
		AC-LINK	<i>Last State</i>	
		Power On Delay Time	<i>20</i>	
		Platform Event Filtering	<i>Enabled</i>	
Boot	1		USB FDC	
	2		USB CDROM	
	3		USB KEY	
	4		IDE CD	
	5		PCI BEV: IBA GE Slot 0C00 v1236	
	6		PCI SCSI	
	7			
	8			

Glossary and Acronyms

A

ACT

Administration Configuration Tool

B

BAS

Bull Advanced Server

BIOS

Basic Input Output System

BMC

Baseboard Management Controller

C

CLI

Command Line Interface

D

DDN

Data Direct Networks

DHCP

Dynamic Host Configuration Protocol

E

ECT

Embedded Configuration Tool

F

FDA

Fibre Disk Array

FRU

Field Replaceable Unit

FTP

File Transfer Protocol

G

GCC

GNU C Compiler

GNU

GNU's Not Unix

GPL

General Public License

GUI

Graphical User Interface

GUID

Globally Unique Identifier

H

HBA

Host Bus Adapter

HPC

High Performance Computing

I

IPMI

Intelligent Platform Management Interface

K

KSIS

Utility for Image Building and Deployment

L

LAN

Local Area Network

LDAP

Lightweight Directory Access Protocol

LUN

Logical Unit Number

M

MAC

Media Access Control (address)

MPI

Message Passing Interface

N

NFS

Network File System

NIS

Network Information Service

NS

NovaScale

NTP

Network Type Protocol

P

PCI

Peripheral Component Interconnect (Intel)

R

RAID

Redundant Array of Independent Disks

S

SCSI

Small Computer System Interface

SLURM

Simple Linux Utility for Resource Management

SMP

Symmetric Multi Processing

SMT

Symmetric Multi Threading

SNMP

Simple Network Management Protocol

SOL

Serial Over LAN

SSH

Secure Shell

T

TCP

Transmission Control Protocol

TFTP

Trivial File Transfer Protocol

U

UDP

User Datagram Protocol

USB

Universal Serial Bus

W

WWPN

World – Wide Port Name

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E-Mail: srv.Duplicopy@bull.net

Reference	Designation	Qty
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[_ _] : The latest revision will be provided if no revision number is given.		

NAME: _____ **DATE:** _____

COMPANY: _____

ADDRESS: _____

PHONE: _____ **FAX:** _____

E-MAIL: _____

For Bull Subsidiaries:

Identification: _____

For Bull Affiliated Customers:

Customer Code: _____

For Bull Internal Customers:

Budgetary Section: _____

For Others: Please ask your Bull representative.

BULL CEDOC
357 AVENUE PATTON
B.P.20845
49008 ANGERS CEDEX 01
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REFERENCE
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